

DOPPLER RADAR OBSERVATIONS AND ENSEMBLE-BASED DATA ASSIMILATION FOR CLOUD-RESOLVING HURRICANE PREDICTION

Fuqing Zhang
Penn State University

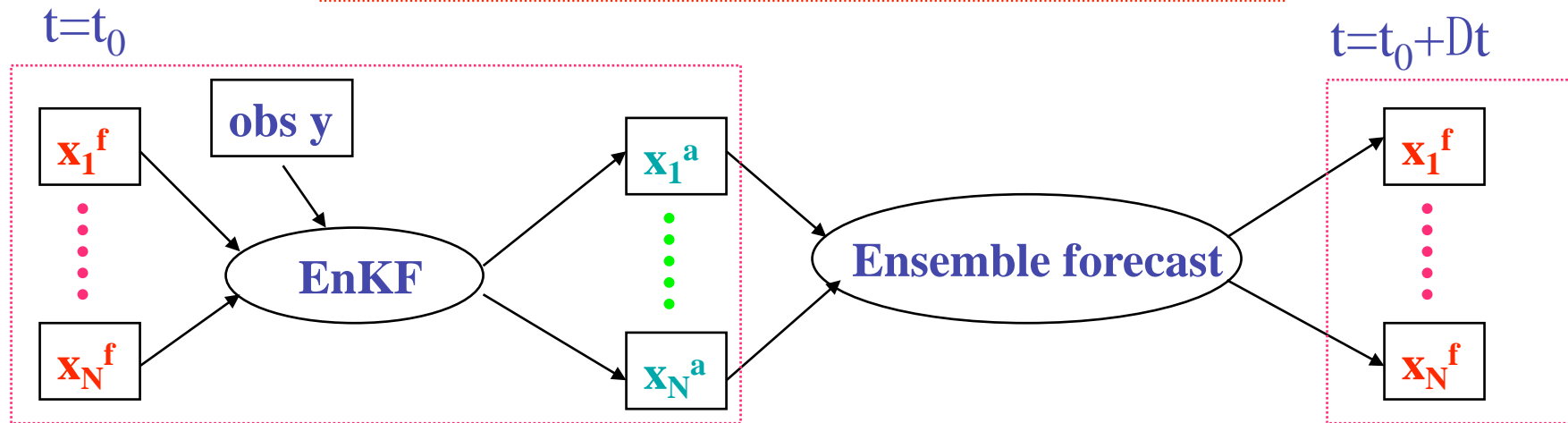
**Contributors: Yonghui Weng, Jason Sippel, Zhiyong Meng, Craig Bishop,
John Gamache and Frank Marks**

Acknowledgements: Support from NSF, ONR, NOAA, TCEQ and TACC

Ensemble Kalman Filter for Mesoscales

(Evensen 1994 JGR; Zhang and Snyder 2007 BAMS)

$$\mathbf{x}^a = \mathbf{x}^f + \mathbf{B}\mathbf{H}^T(\mathbf{H}\mathbf{B}\mathbf{H}^T + \mathbf{R})^{-1}(\mathbf{y} - \mathbf{H}\mathbf{x}^f)$$



Ensemble forecast provides better, flow-dependent estimate of background error covariance: $\mathbf{B} = \mathbf{N}_e^{-1} \sum (\mathbf{x}_i^f - \underline{\mathbf{x}})(\mathbf{x}_i^f - \underline{\mathbf{x}})^T$

Equivalence to 4Dvar in linear systems; no adjoint or TLM; fully coupled with ensemble forecast; nonlinear dynamics included; adaptable to be coupled/hybrid with 3D/4DVar

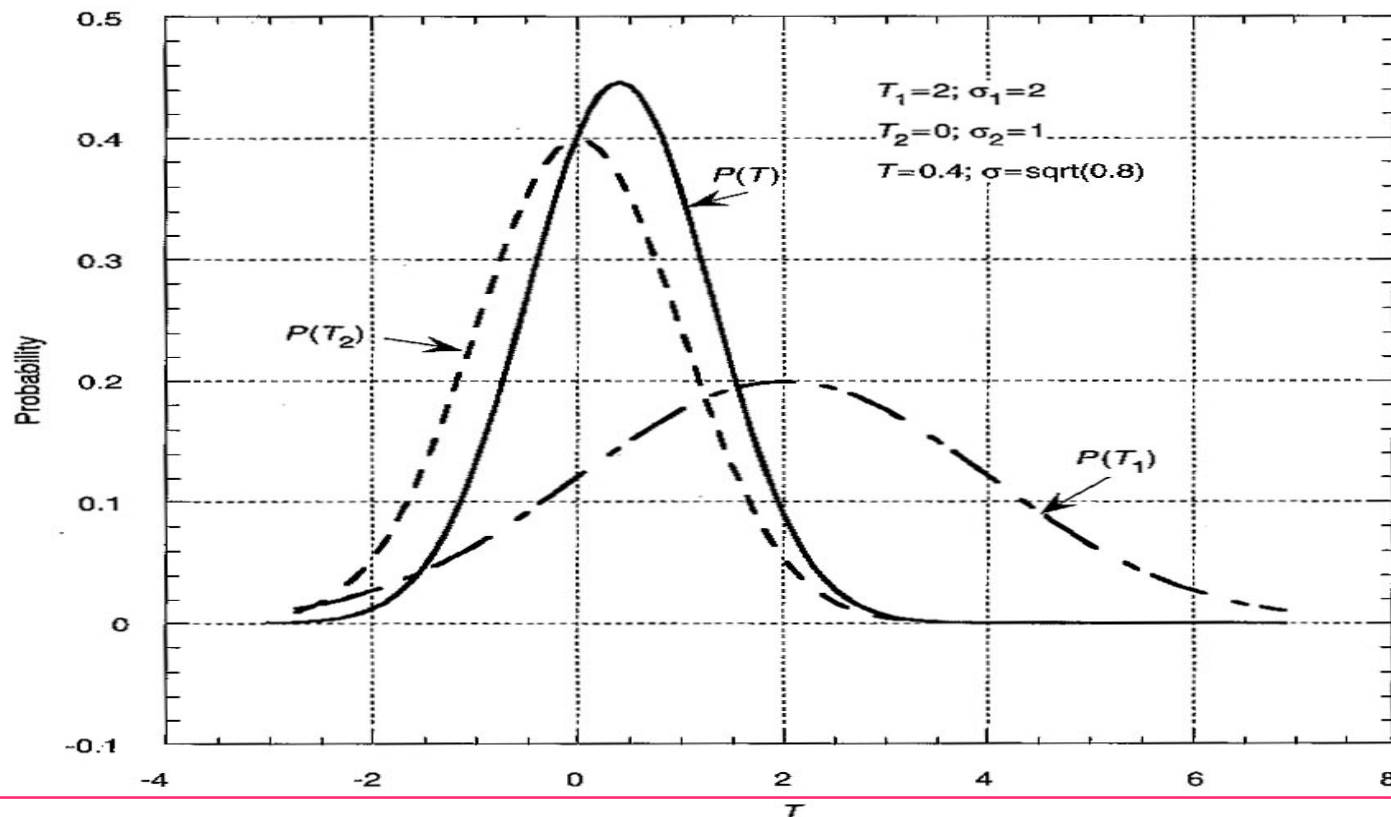
A Simple Example

If T_1 is the background state with std of σ_1 ; T_2 is the observation with std of σ_2 , then the posterior analysis T and its std σ will be:

$$T = T_1 + K (T_2 - T_1); \quad K = \sigma_1^2 / (\sigma_1^2 + \sigma_2^2)$$

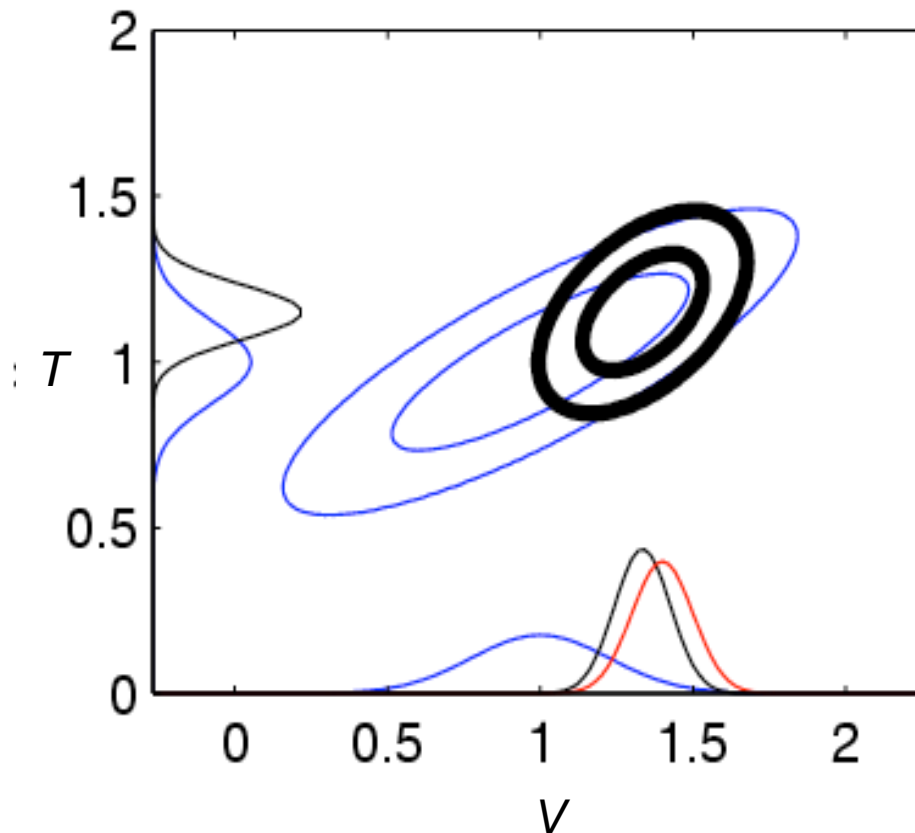
$$\text{or } T = [\sigma_2^2 / (\sigma_1^2 + \sigma_2^2)] T_1 + [\sigma_1^2 / (\sigma_1^2 + \sigma_2^2)] T_2$$

$$\sigma^2 = \sigma_1^2 \sigma_2^2 / (\sigma_1^2 + \sigma_2^2)$$



A Multivariate Example

If T_1 is unobserved but with measurements of V_2 (e.g., radar radial velocity obs), then the posterior analysis T depends on background error covariance $\text{Cov}(T, V)$:



$$T = T_1 + K (V_2 - V_1)$$

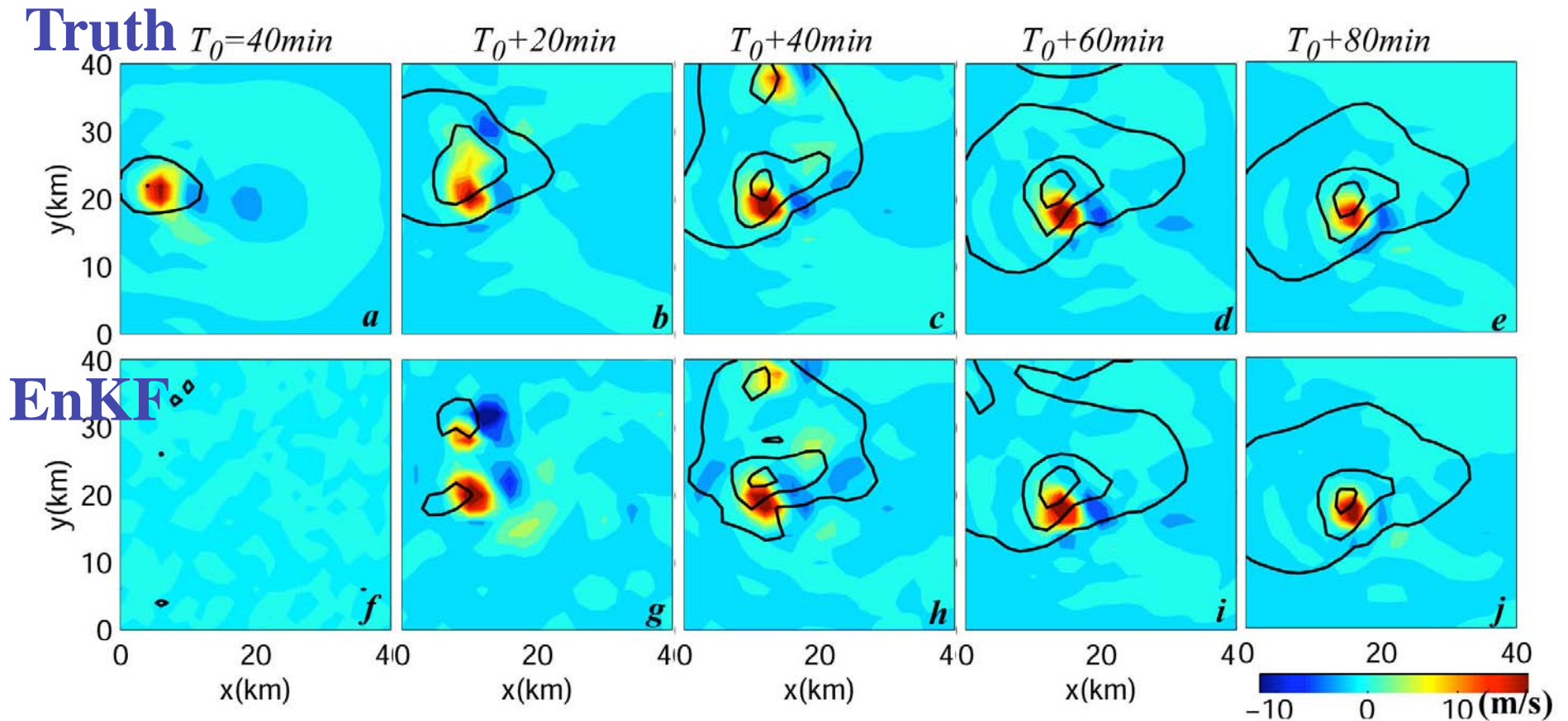
$$K = \text{Cov}(T, V) / (\sigma_{v1}^2 + \sigma_{v2}^2)$$

In EnKF, $\text{Cov}(T, V)$ is estimated by short-range ensemble and is flow-dependent

Assimilation of Doppler Radar Observations

Observations: radial velocity V_r only, available every 5 minutes where reflectivity $Z > 12\text{dBZ}$

Vertical velocity at 5km (colored) and surface cold pool (black lines, every 2K)

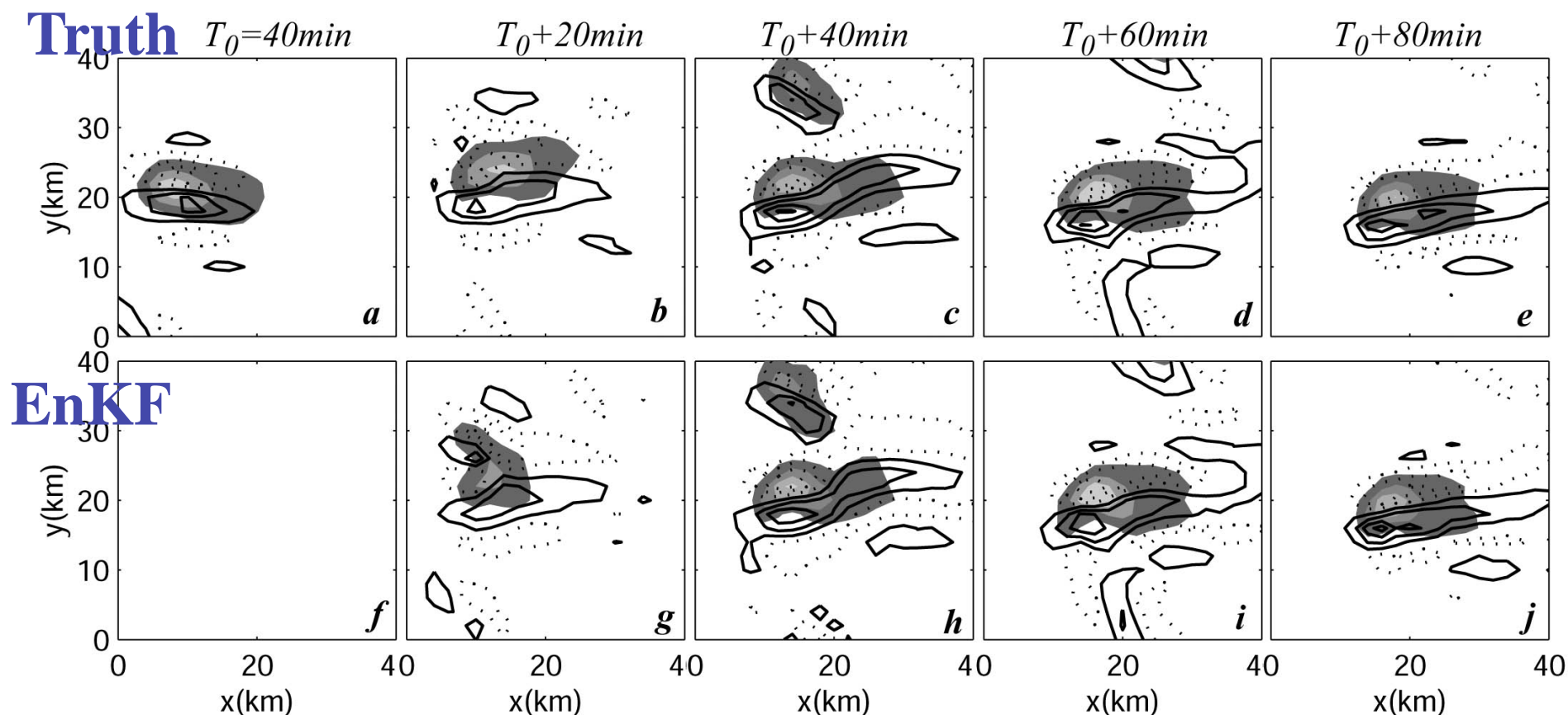


(Snyder and Zhang 2003 MWR; Zhang et al. 2004 MWR; Dowell, Zhang et al. 2004 MWR)

Assimilation of Doppler Radar Observations

Observations: radial velocity V_r only, available every 5 minutes where reflectivity $Z > 12\text{dBZ}$

5-km rain water mixing ratio (shaded) and relative vorticity (solid, >0 ; dotted, <0)



(Snyder and Zhang 2003 MWR; Zhang et al. 2004 MWR; Dowell, Zhang et al. 2004 MWR)

Regional Scale EnKF vs. 3Dvar for June 2003

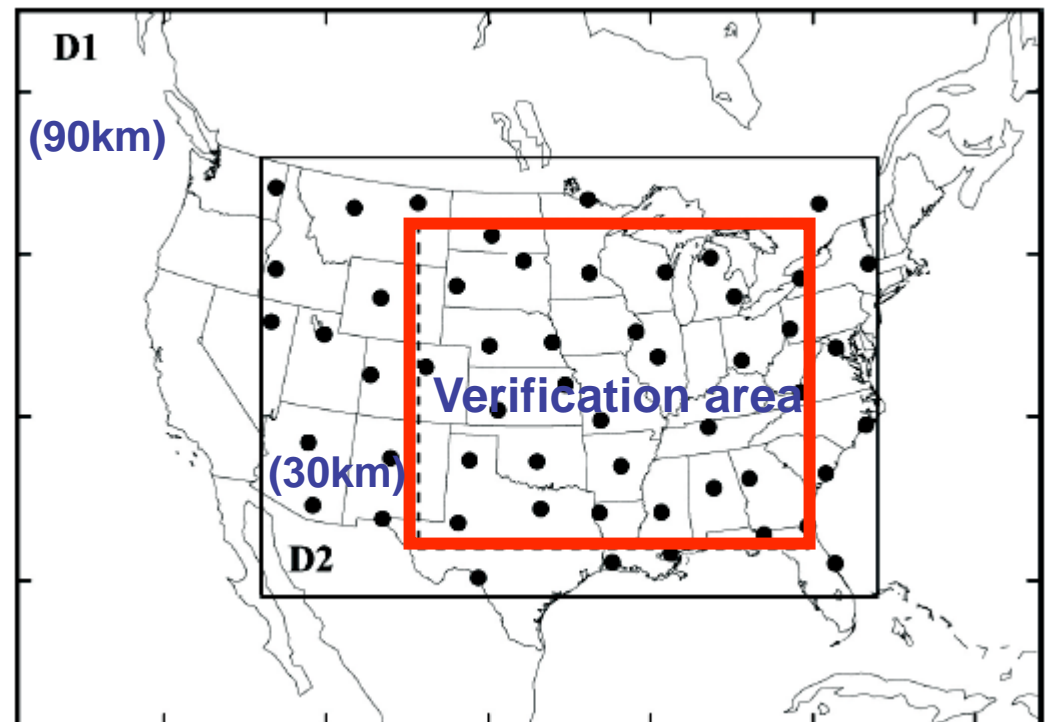
WRF/ARW/EnKF: 40 multi-physics-scheme ensemble

Boundary conditions: D1 updated by 12 hourly GFS/FNL analyses

3DVar: Updated background error covariance with May 2003 forecasts via NMC method (Parrish and Derber 1992; Xiao and Sun 2007)

Observations: Soundings every 12 h QC'd by 3Dvar in D2, assuming observational errors of NCEP.

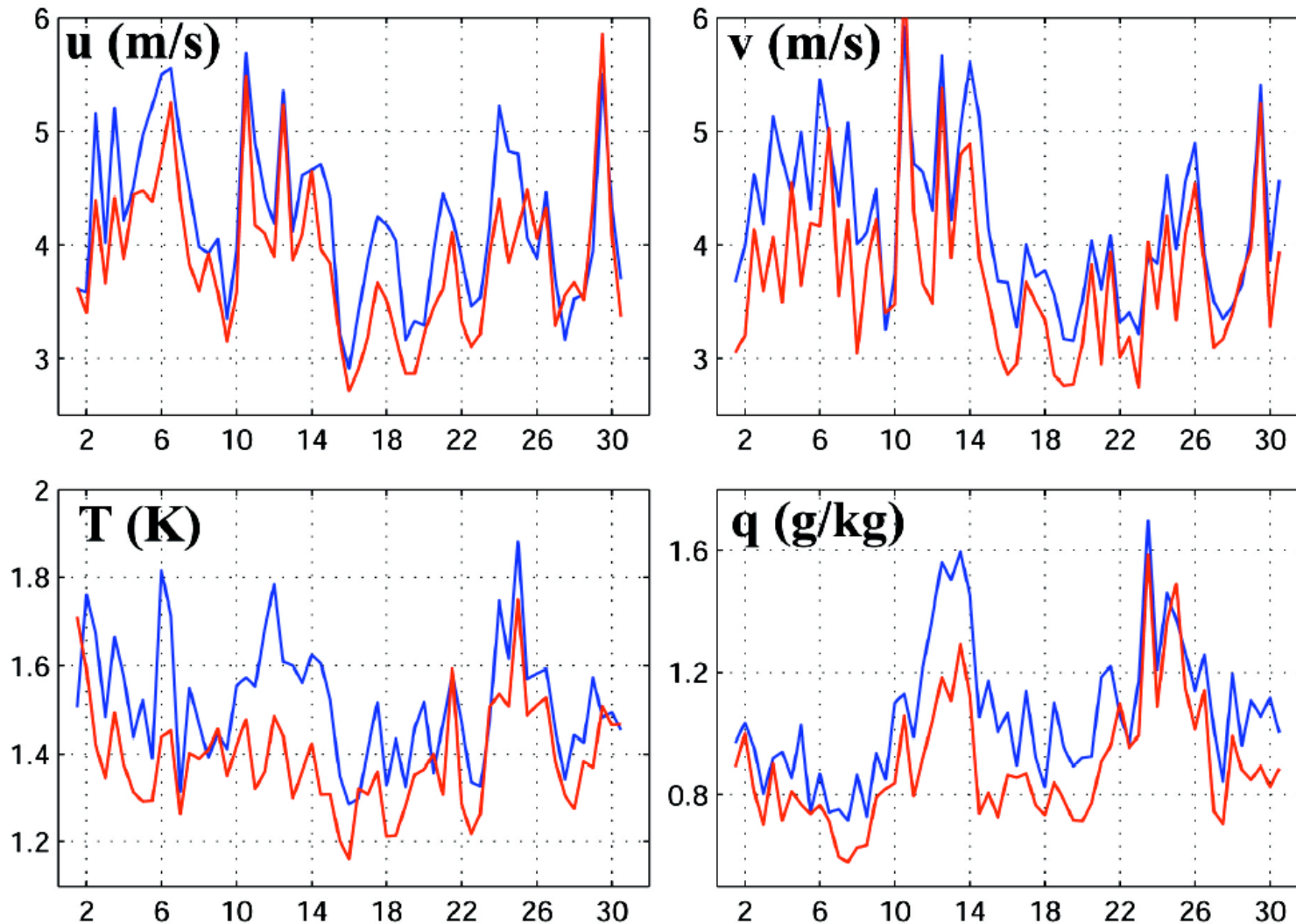
Verification: against soundings at 12-h forecast time and at standard pressure levels



(Zhang, Meng and Aksoy 2006;
Meng and Zhang 2007, 2008a,b MWR)

EnKF vs. 3DVar: WRF/ARW 12h forecast RMSE for Jun'03

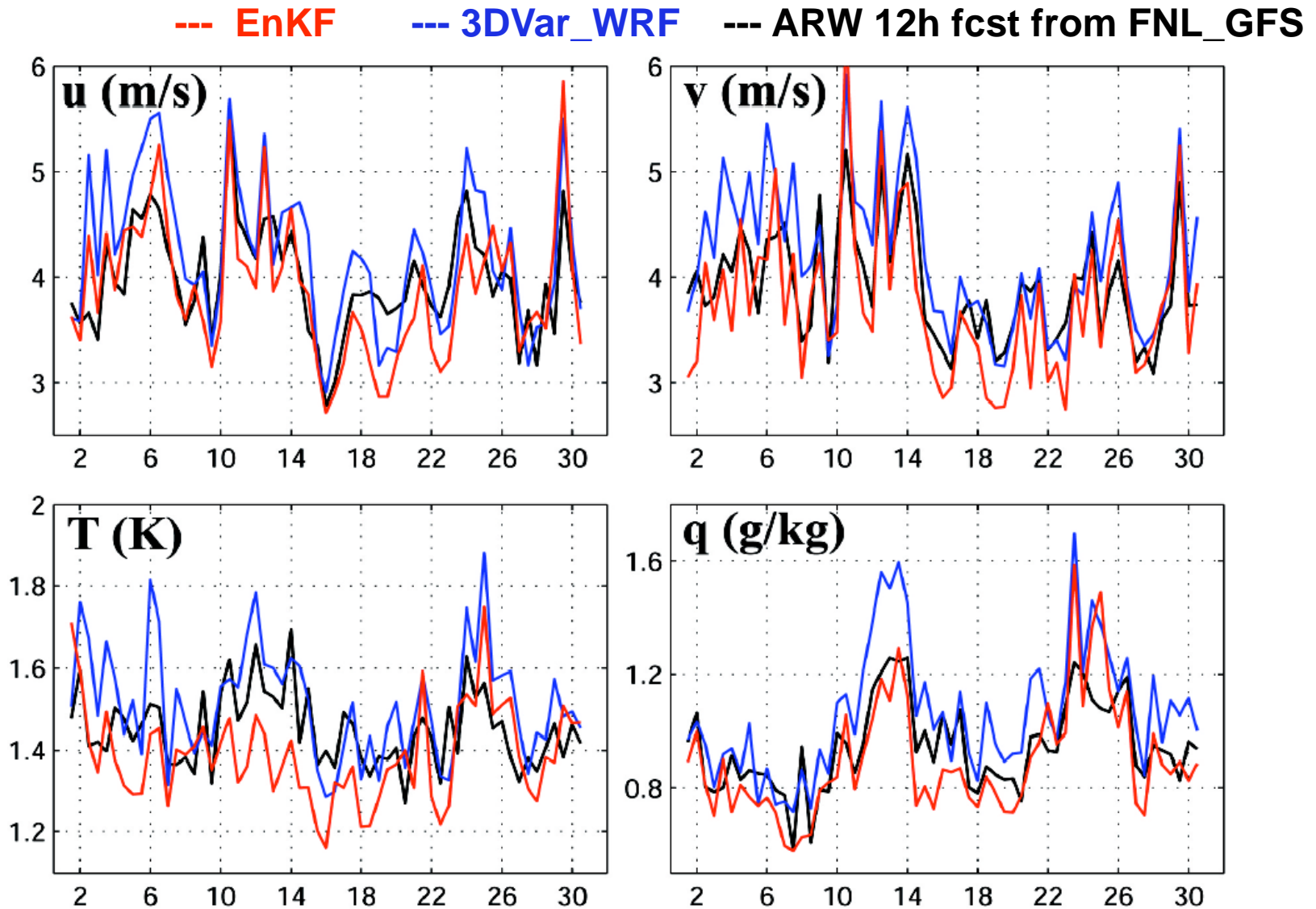
---EnKF --- 3DVar_WRF



EnKF performs generally better than WRF 3DVar for the whole month of June

(Meng and Zhang 2008b MWR)

EnKF vs. 3DVar vs. FNL_GFS for June 2003

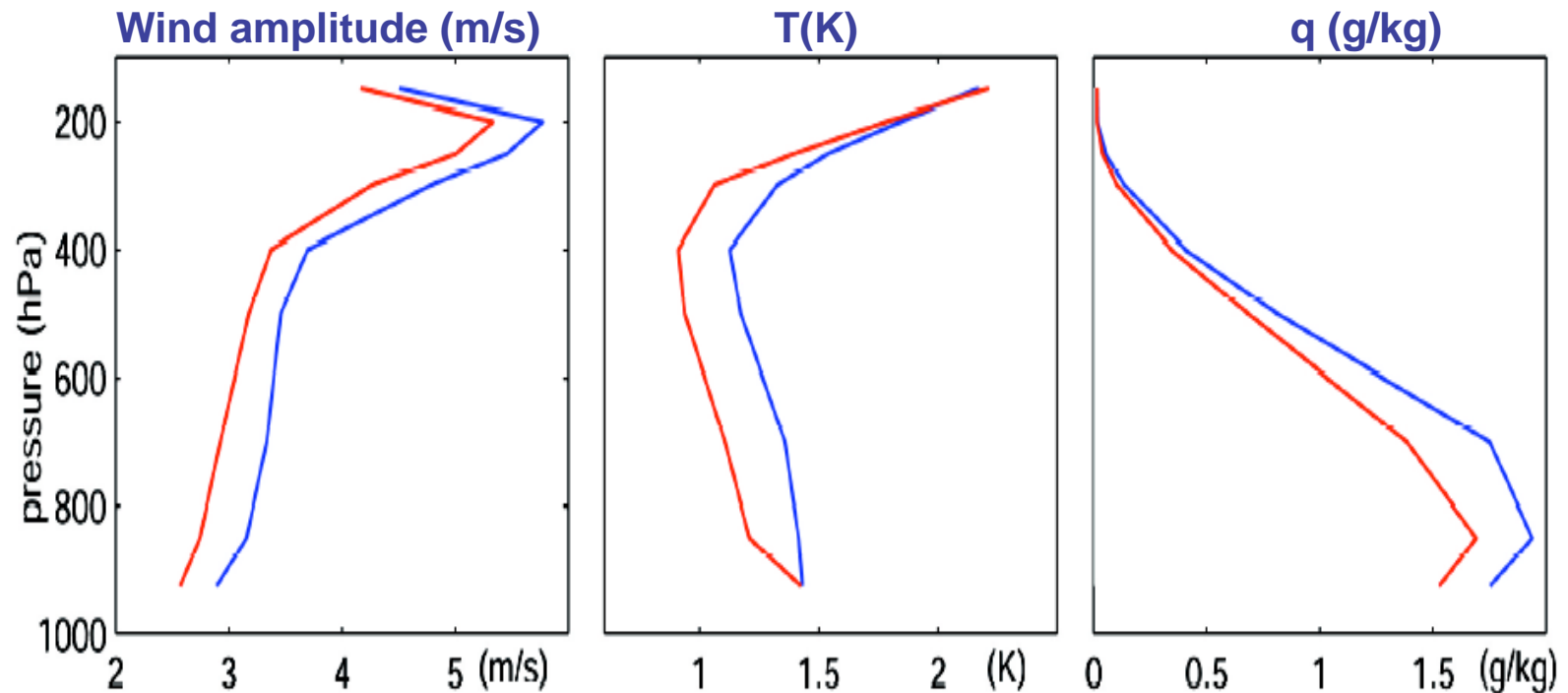


*EnKF performs even better than FNL_GFS which assimilates many more data including satellite
FNL_GFS has a generally smaller 12-h forecast error than wrf-3DVar.*

(Meng and Zhang 2008b)

Vertical Distribution of 12-h Forecast RMSE for June 2003

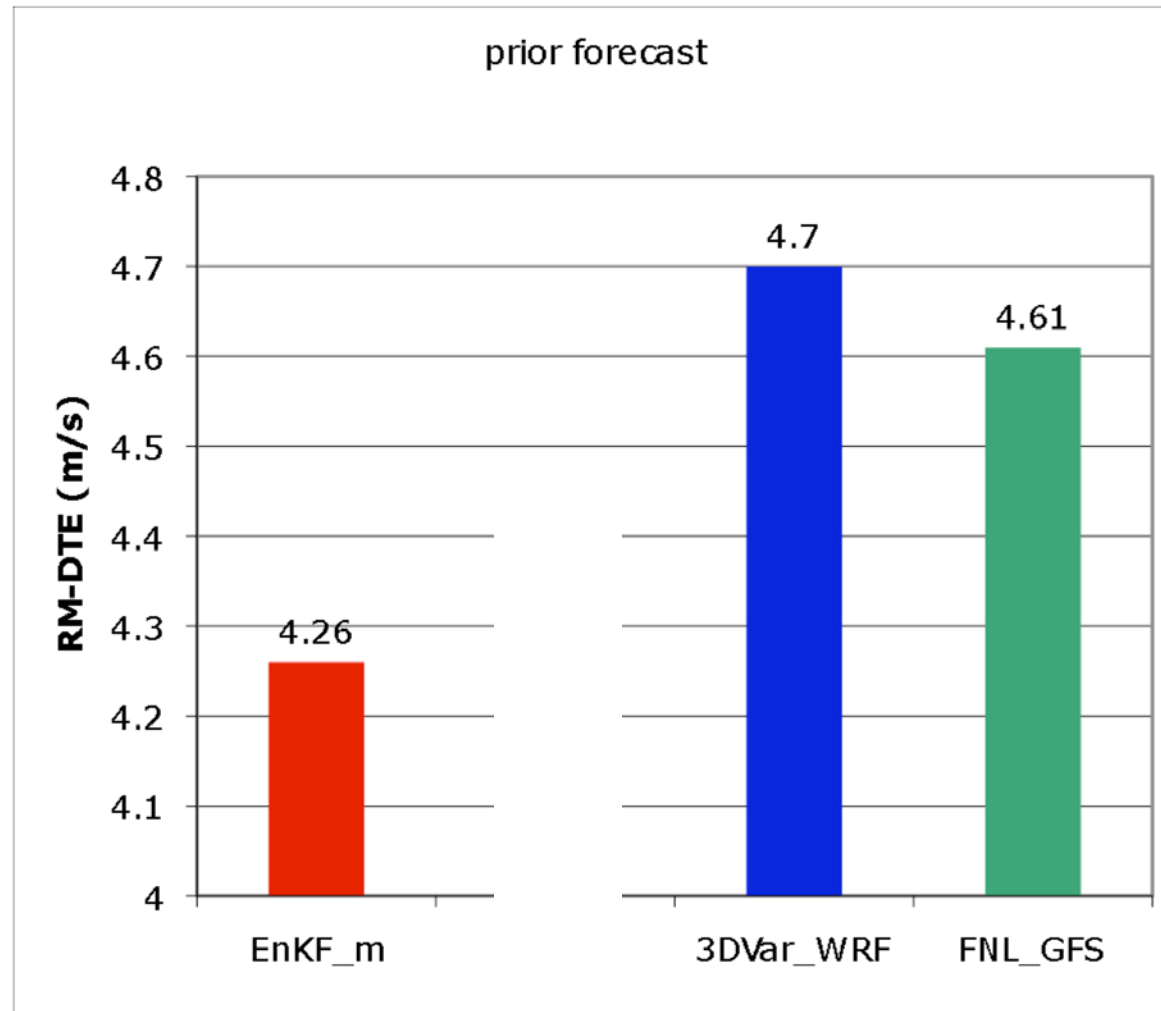
--- EnKF --- 3DVar_WRF



EnKF performs clearly better than WRF-3DVar in almost every vertical level

(Meng and Zhang 2008b)

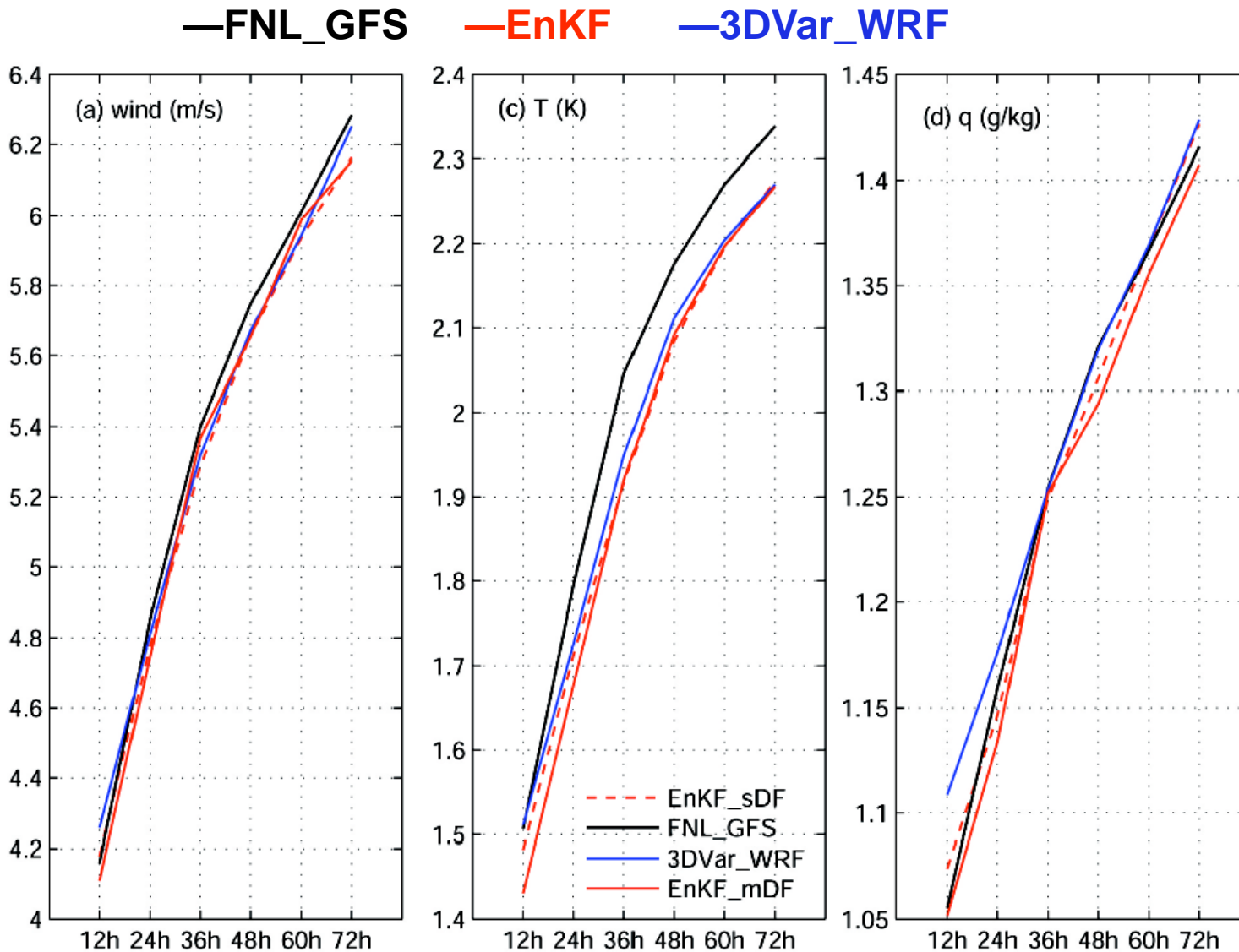
Monthly Averaged 12-h-Forecast RM-DTE for June 2003



- *EnKF has significantly smaller overall 12-h forecast error than both WRF-3DVar and FNL_GFS.*
- *FNL_GFS has smaller overall forecast error than WRF-3DVar.*

(Meng and Zhang 2008b)

Monthly Averaged Forecast Error at Different Lead times initialized from respective analyses (every 12h, 60 samples)

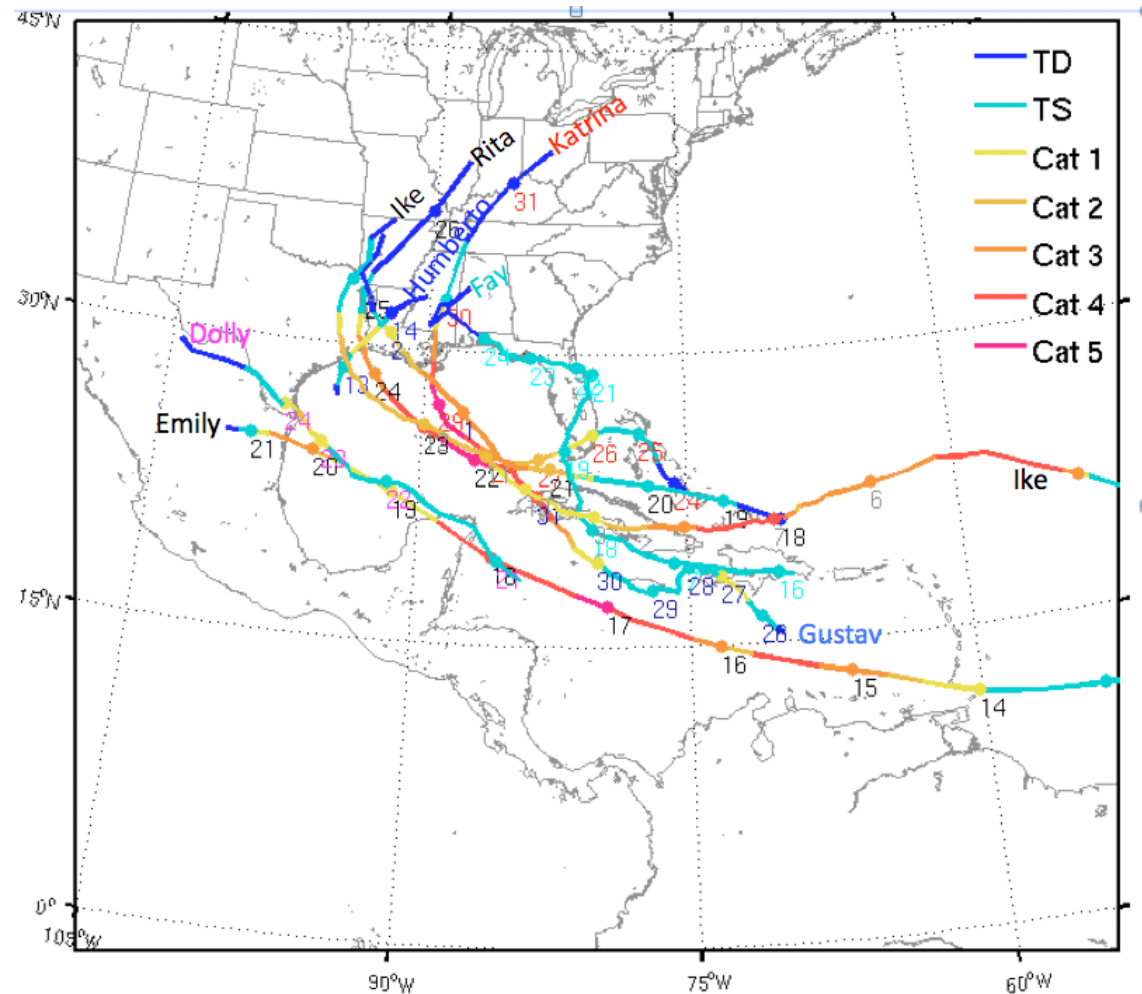


(Meng and Zhang 2008b)

Assimilation of Doppler Vr OBS for Hurricanes

Emily, Katrina, Rita'05, Humberto'07, Dolly, Fay, Gustav, Ike'08

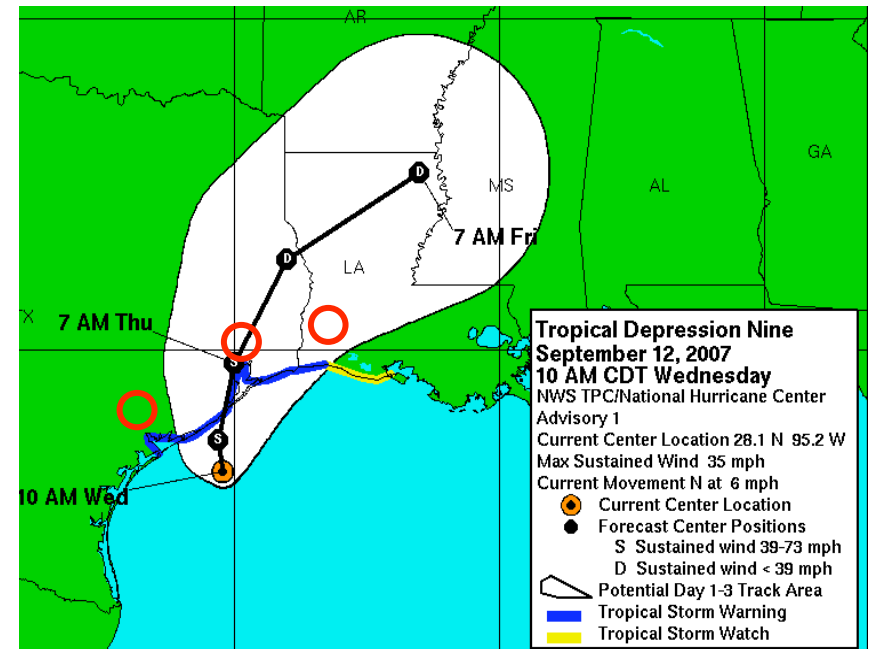
- TC initialization is intrinsically multiscale; initial vortex and convective details can both be important for intensity, structure and precipitation forecasts
- Abundant WSR-88D obs for TCs near coasts
- HRD collects NOAA P3 aircraft radar data sets and process them on most tropical cyclones since 1994.
- NOAA airborne Doppler missions to expand for TCs



Cases with WSR88D or NOAA P3 airborne Vr OBS

Coastal Storms within WSR-88D: Hurricane Humberto (2007)

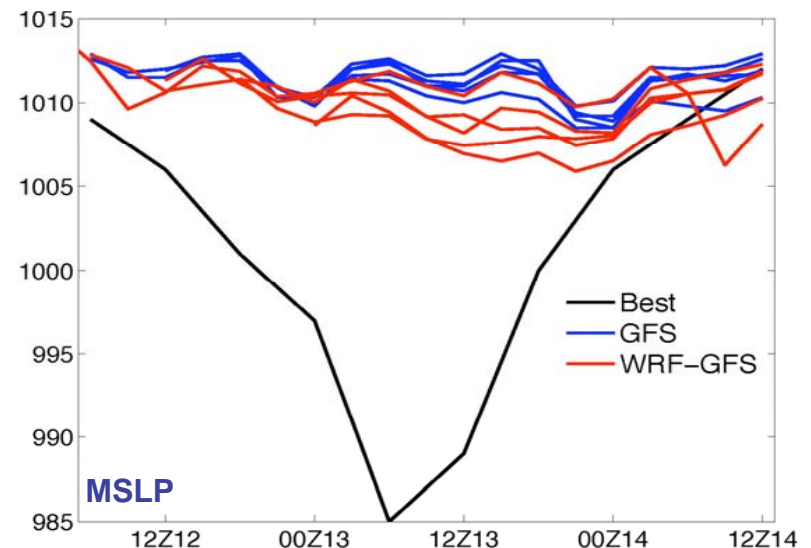
Synopsis: first lanfalling hurricane at US coast since busy 2005 season; fastest from first NHC warning to a category 1 hurricane; 70 million estimated property damage, 1 death



It becomes a hurricane 14hr after this NHC forecast.

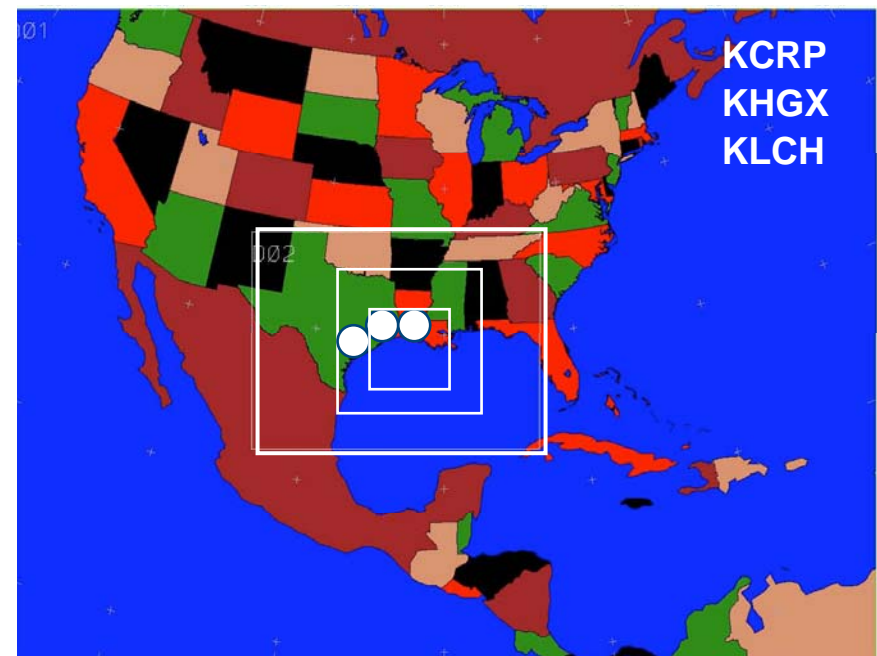
GFS (blue) & 4.5-km WRF (red) forecast: No forecast initialized with GFS FNL analysis ev 6hr from 00Z 12 to 00Z 13 predicts rapid formation

(Zhang et al. 2008, MWR, in review)

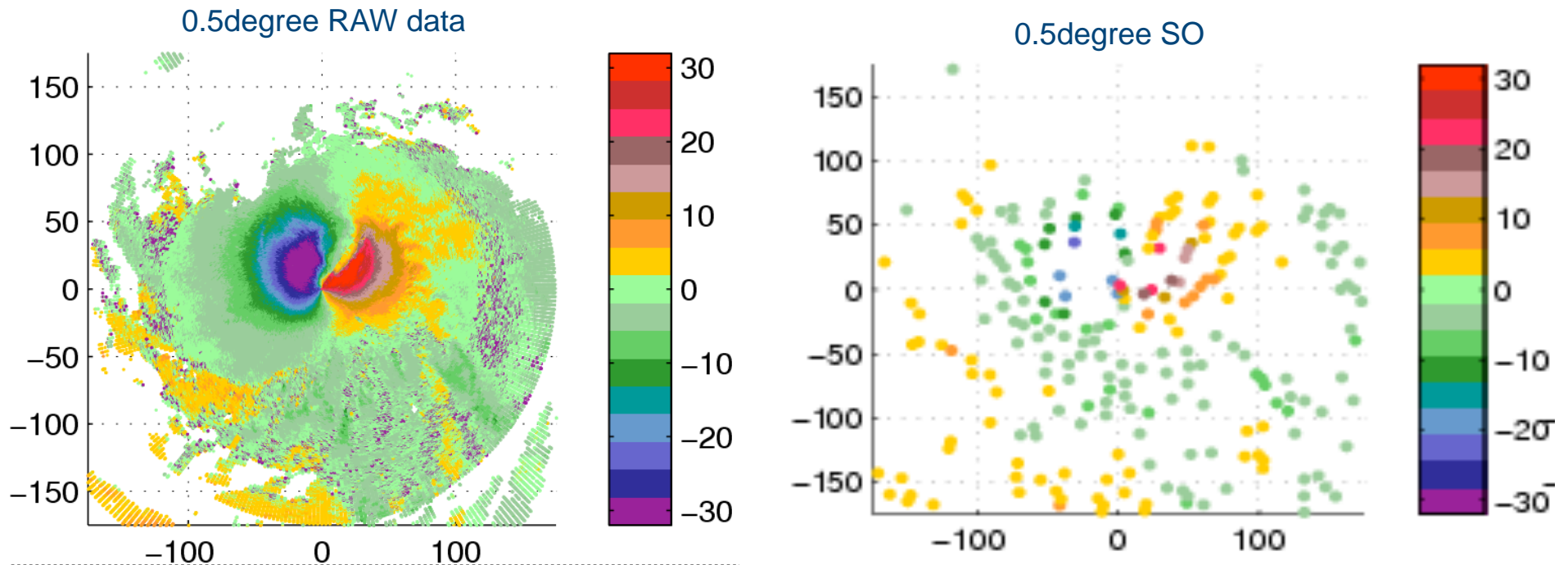


Assimilate W88D Vr for Humberto with EnKF

- **WRF domains:** D1-D2-D3-D4 grid sizes---40.5, 13.5, 4.5, 1.5km (movable)
 - **Physics:** WSM 6-class microphysics; YSU PBL; Grell-Devenyi CPS
- **EnKF (Evensen 1994; Meng & Zhang 2008a,b):** - 30-member ensemble
 - Initialized at 00Z 12 using 3DVar background uncertainty with FNL analysis; GFS forecast used for boundary condition in forecasts
 - **Advantage:** flow-dependent background error covariance from ensemble; flow dependent analysis uncertainty for ensemble forecasting
- **Data assimilated:**
 - WSR88D at KCRP, KHGX and KLCH radar radial velocity every hour from 09Z to 21Z 12 Sept 2007
 - Data assimilation are performed for all domains; obs err 3m/s

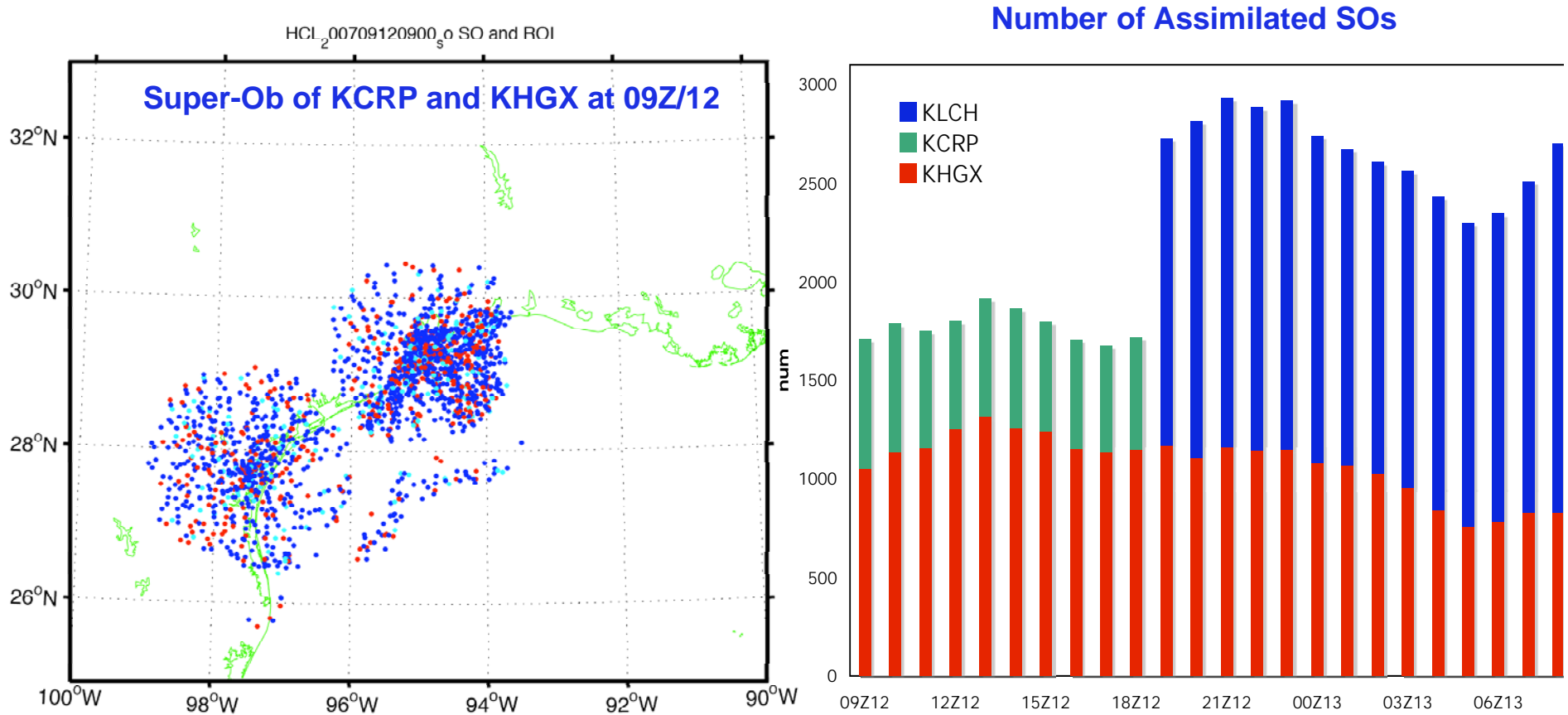


Super-Obs: QC and thinning of WSR-88D Vr Obs



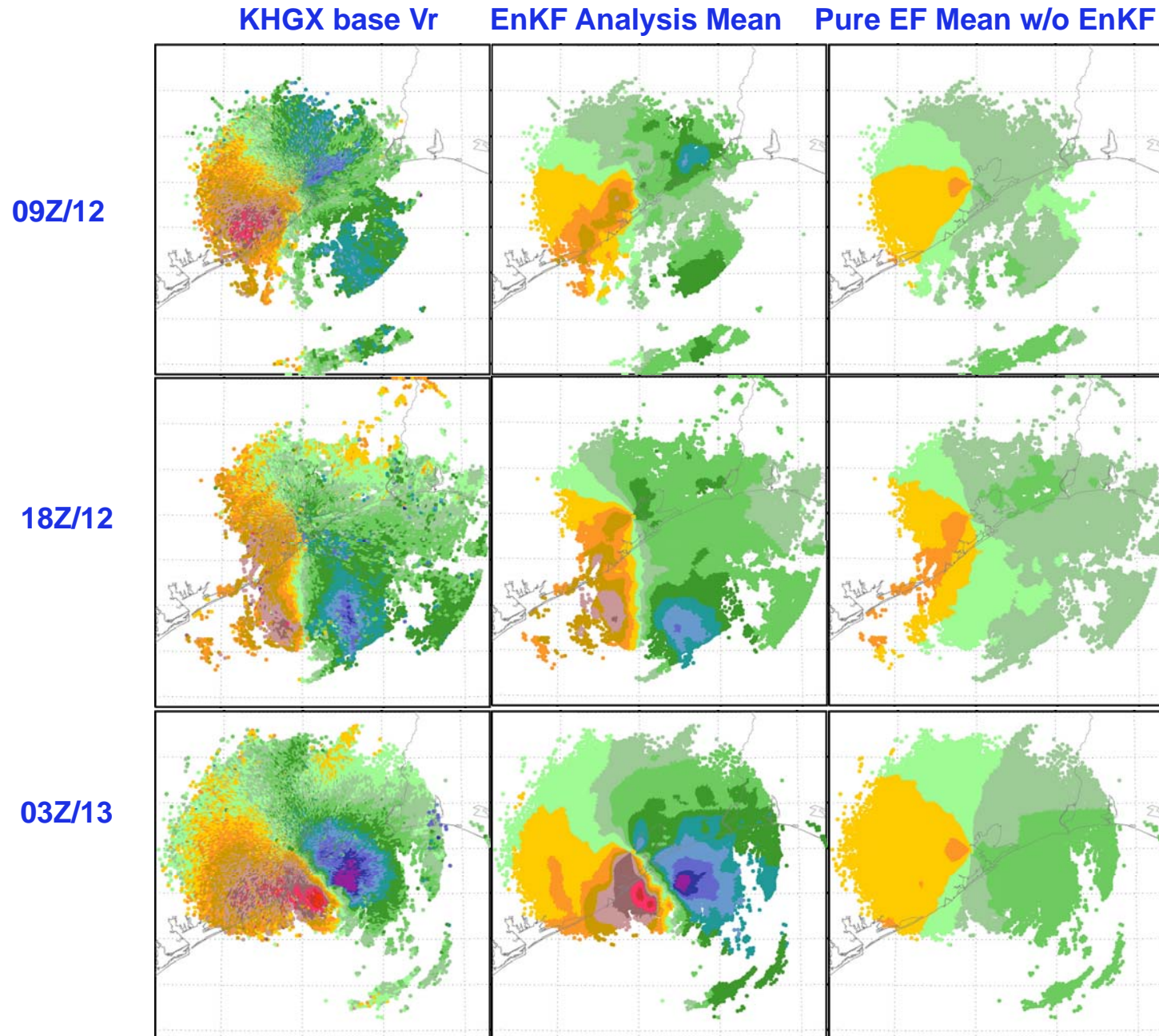
- Define SO position depended on the radial distance
- Average 10 nearest data points in the raw polar scan to create a SO
- Averaging bin is 5km max radial range and 5° max azimuthally resolution
- There are at least 4 valid velocity data within an averaging bin.
- The standard deviation checking of the velocities.

Assimilate WSR88D Vr Obs: Number of SOs

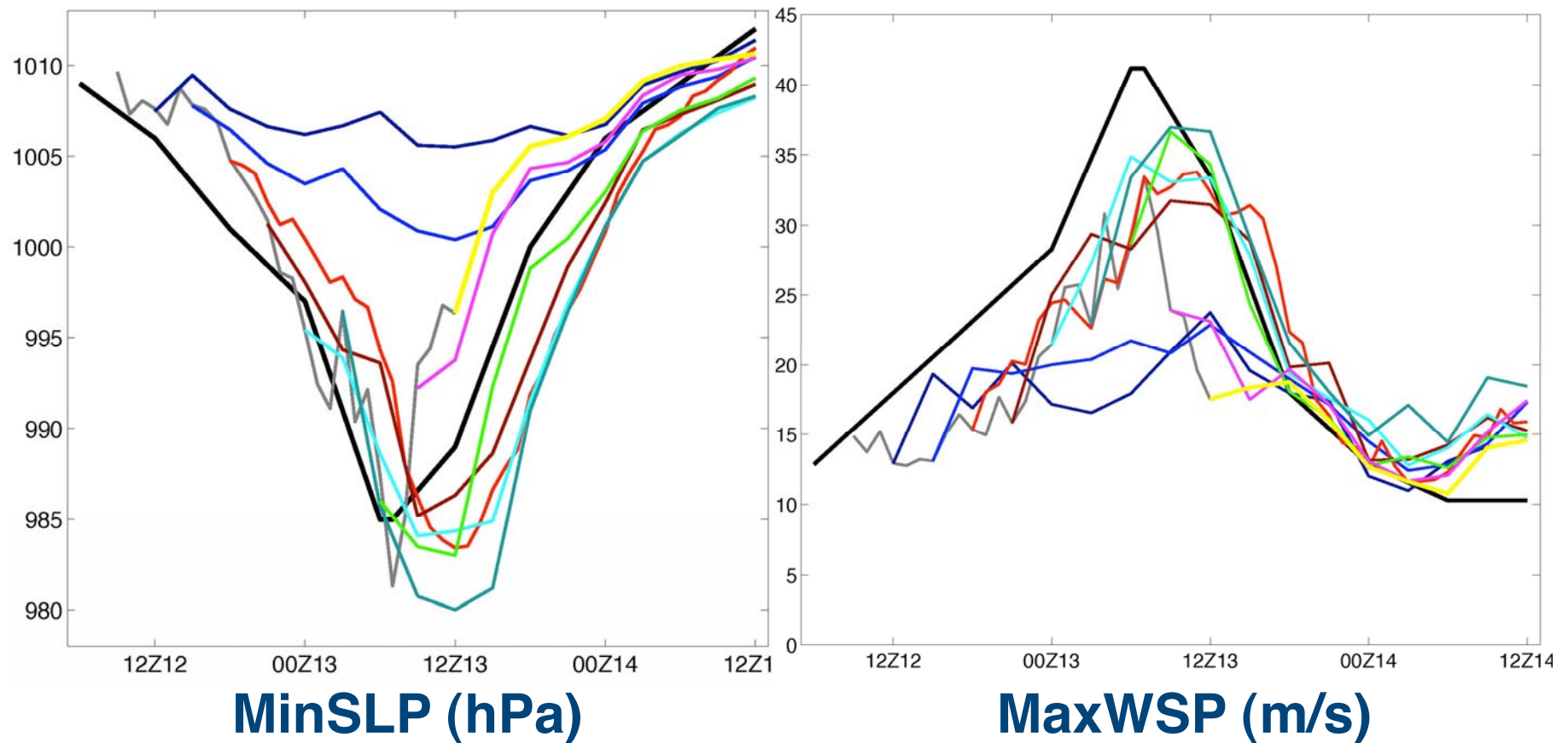


- WRF/EnKF starts assimilating hourly Vr obs of CRP, HGX and LCH WSR88D radars from 09Z/12 to 21Z/12 after a 9-h ensemble forecast from GFS/FNL analysis
- Successive covariance localization with different ROIs for different subset of SOs

CNTL EnKF Analysis vs. KHGX Obs vs. NoDA

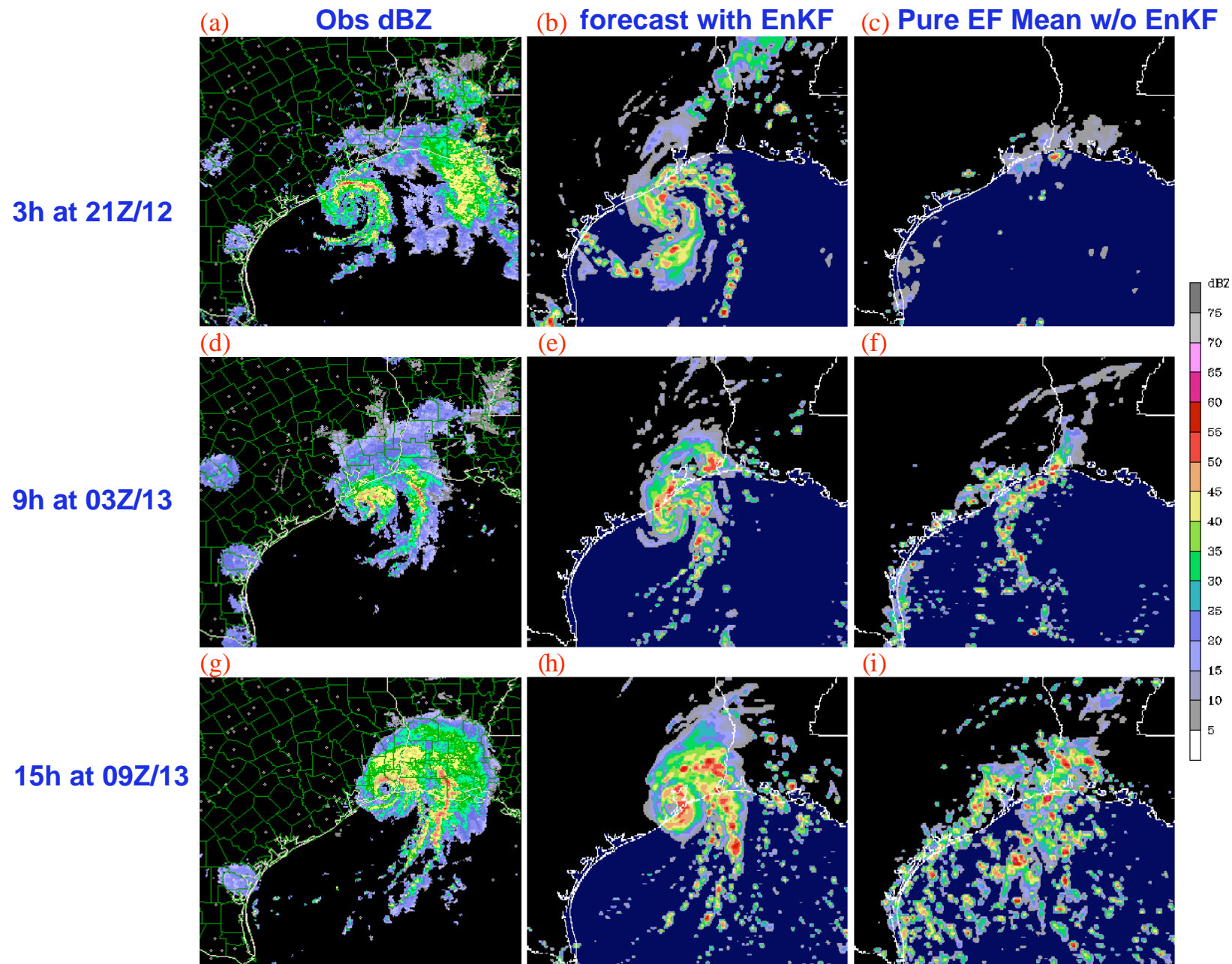


Forecast initialized with EnKF Assimilating WSR88D Vr

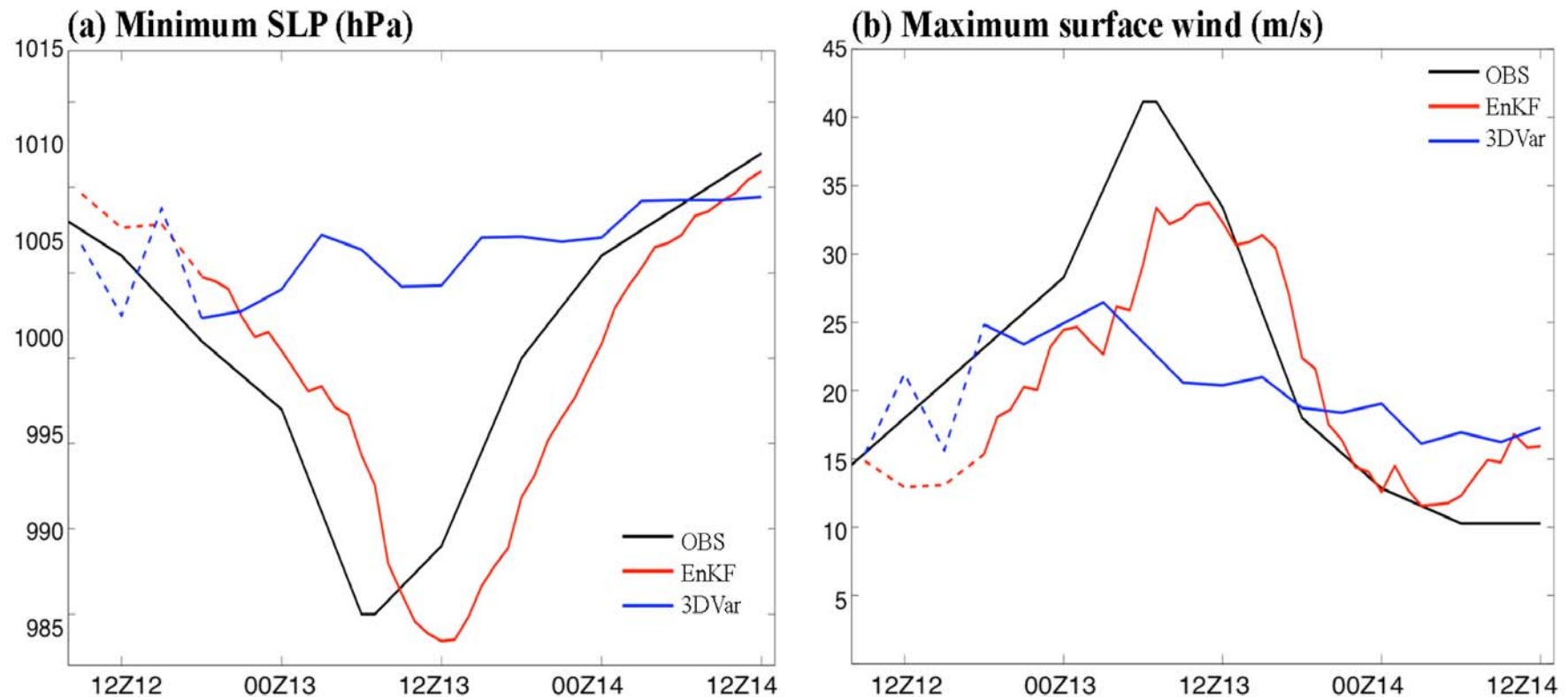


WRF single forecasts initialized with EnKF analysis at 18Z or 21Z September 12 captures well the rapid TC formation and deepening (red and brown)

Forecast from EnKF Analysis at 18Z/12

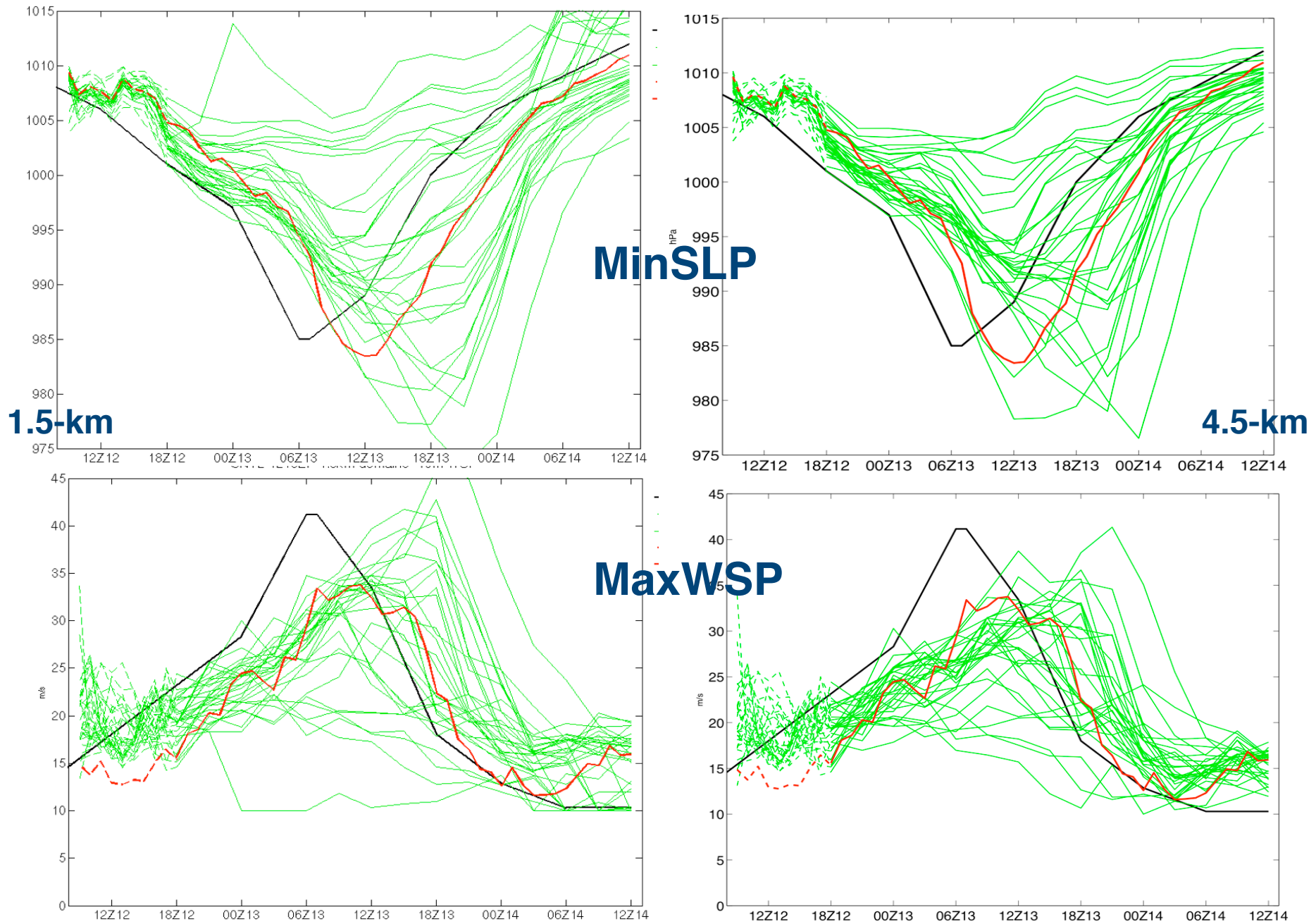


Comparison with WRF/3DVAR Assimilating the Same OBS



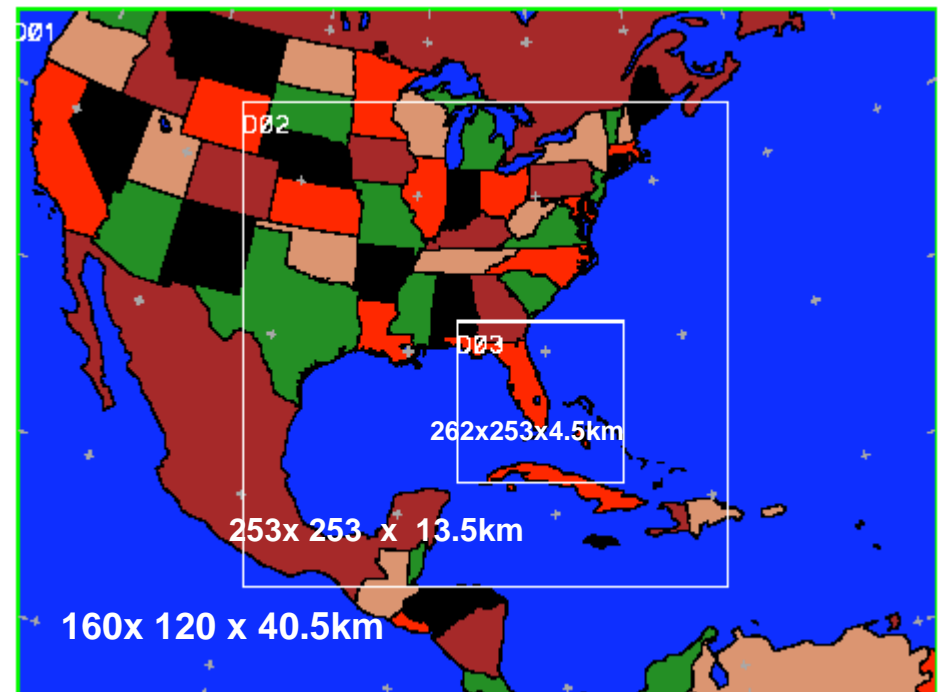
Without flow-dependent background error covariance, WRF/3DVAR forecast failed to develop the storm despite fit to the best-track obs better at 18Z

Predictability: 1.5-km (left) vs. 4.5-km (right) 42h ensembles

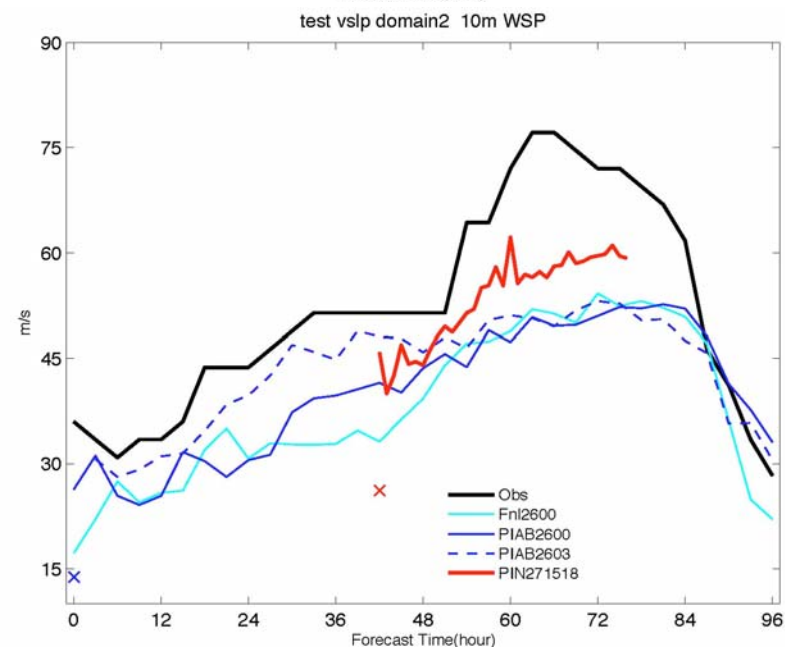
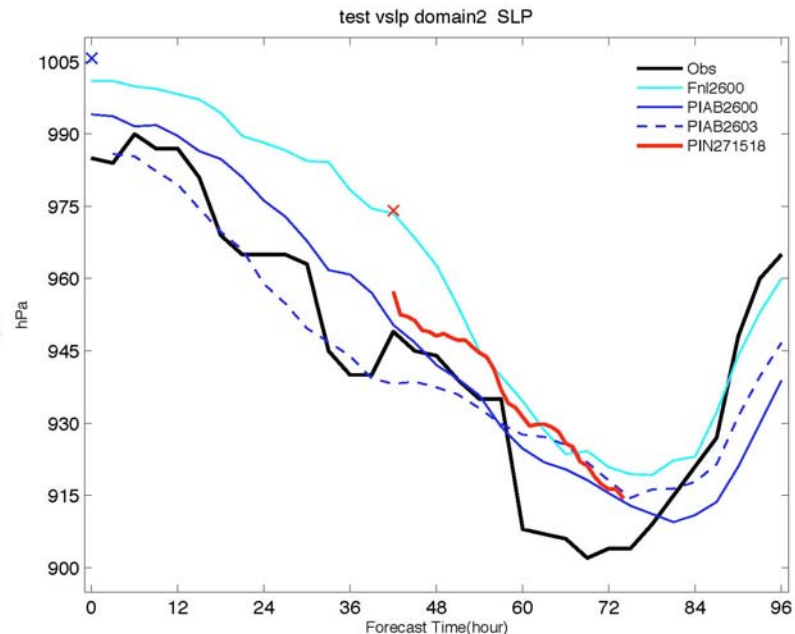
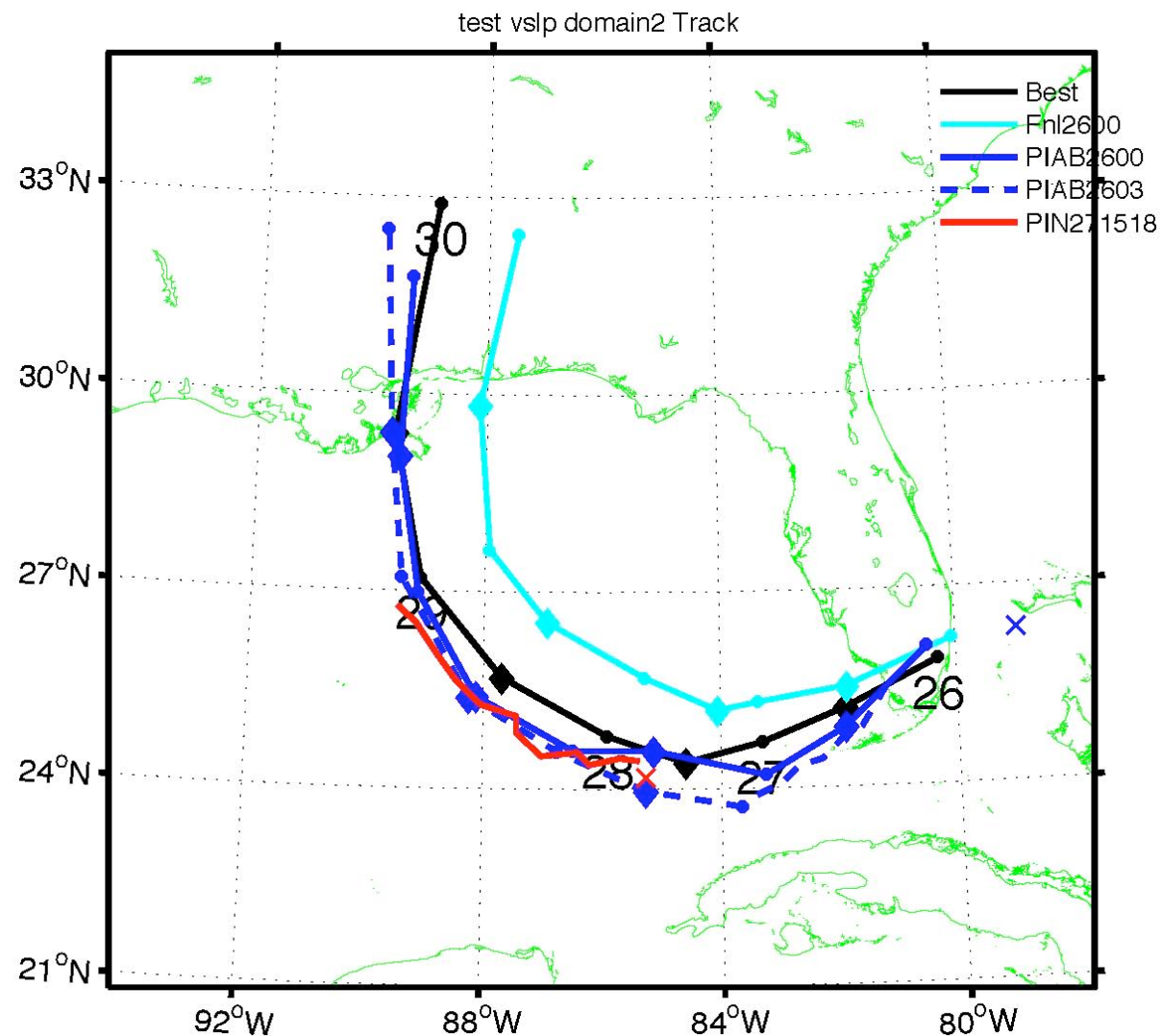


WRF/EnKF for Katrina with W88D Data

- WRF domains D1-D3: 40.5, 13.5, 4.5 km ; 35 vertical levels; WSM 6-class microphysics; YSU PBL; Grell-Devenyi CPS
- EnKF (Meng & Zhang 2008a,b) but with 30-member single-scheme ensemble; Gaspari&Cohn 99' covariance localization but with varying RoI
- IC & BC: FNL analysis using 3DVAR background uncertainty
- Data assimilated:
 - TC position (err=20km) and intensity (err=1hpa) D1,D2 every 3 h from 0Z/25 to 0Z/26 (Chen and Snyder 2007)
 - Doppler velocity (err=3m/s) from KMAX and KBYX (D1, D2) at 00Z/26 and/or 03 & 06Z
- Forecast: 96-h single run from mean analysis with D1, D2, D3 (two-way) w/ D3 movable



EnKF Performance: Track forecast with Vr assimilated



NEXRAD at KAMX and KBYZ assimilate at 00Z 26 Aug in 14.5-km D2; free forecast with 4.5-km D3 afterwards

Airborne Doppler Radar Scanning Geometry

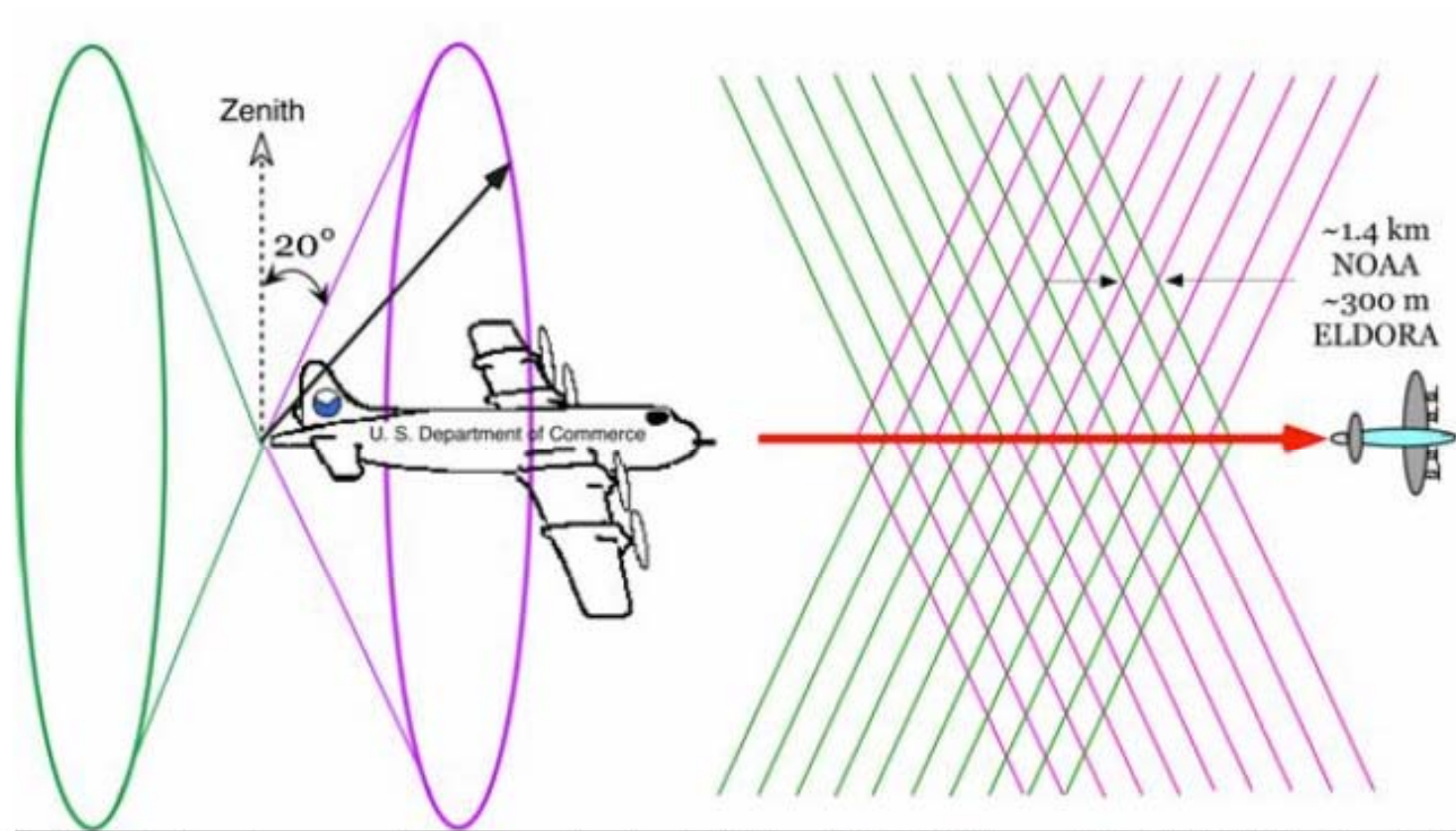
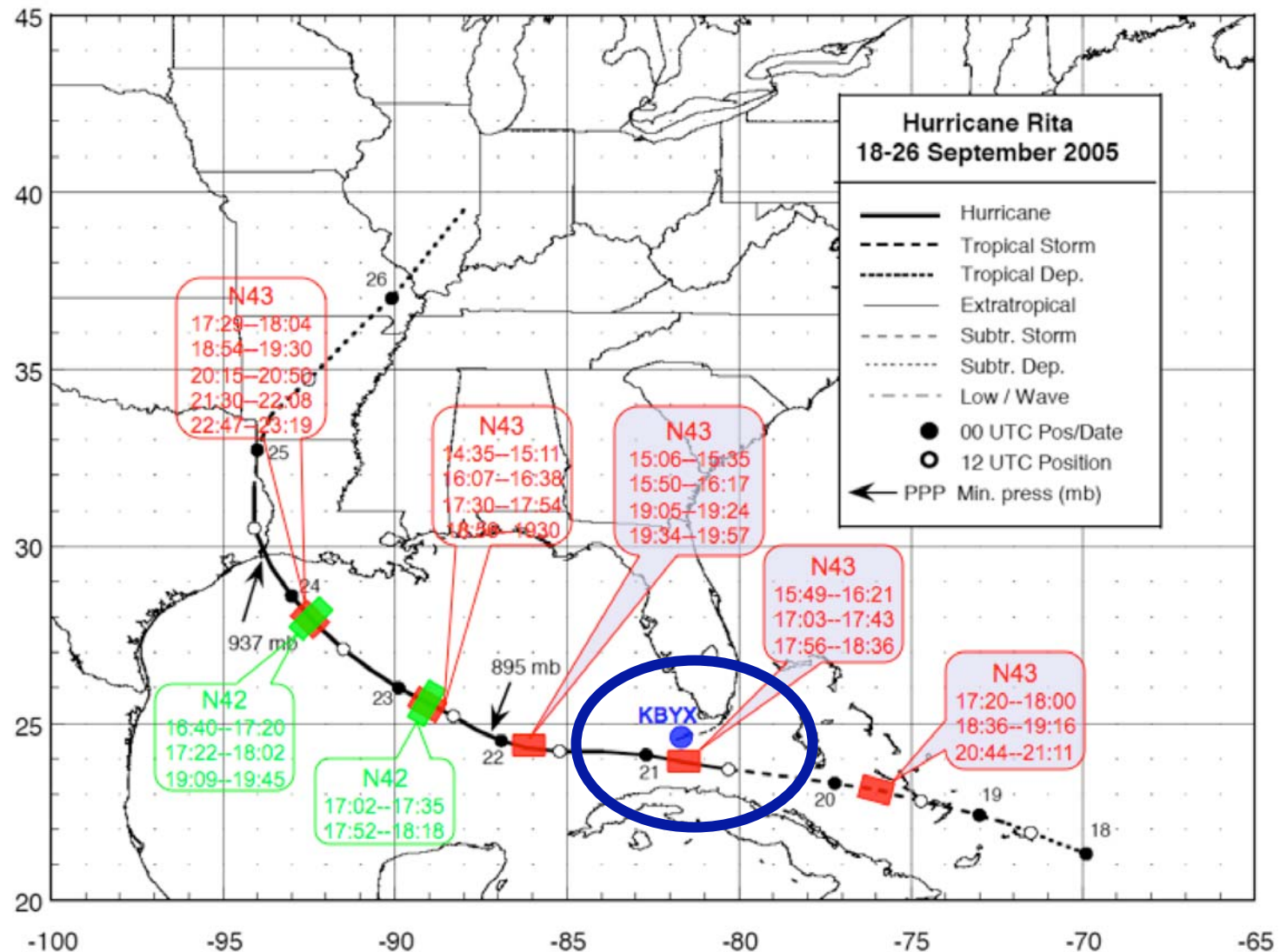


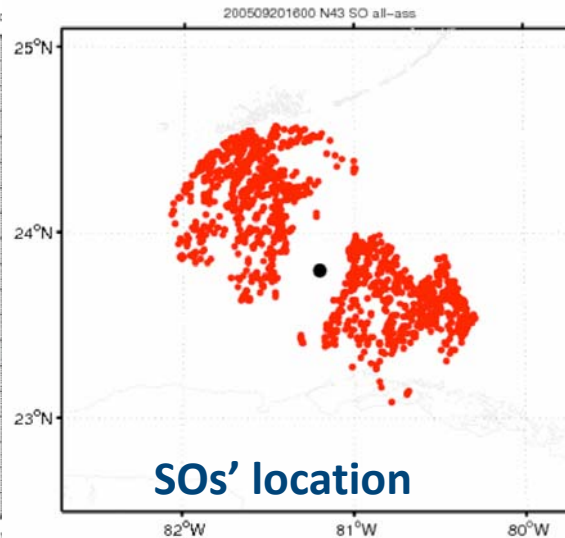
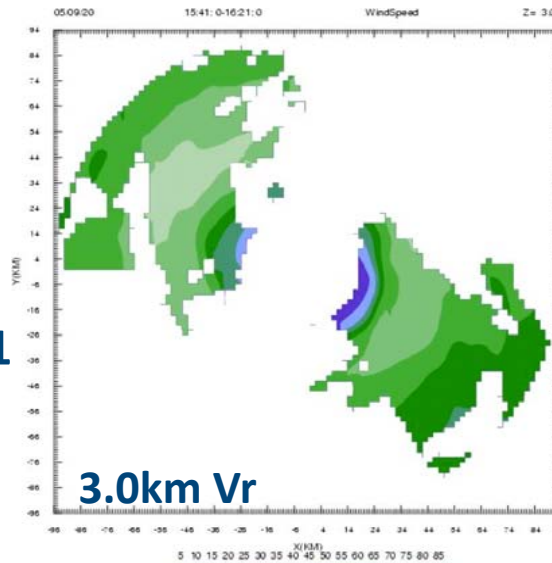
Fig. 2.5 Tail radar scanning geometry for both the NOAA P-3s and the NRL P-3. The left plot shows a schematic of the antenna scanning methodology. A horizontal projection of the beams is shown on the right.

Hurricane Rita (2005): Best track and NOAA P3 Airborne Missions



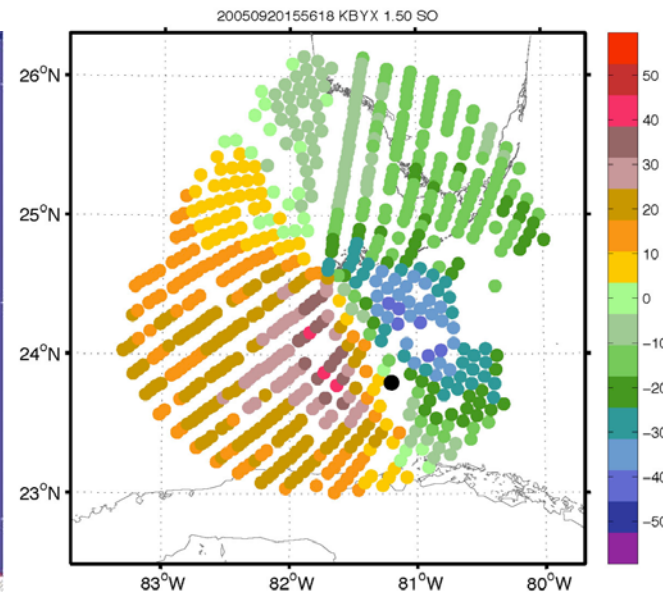
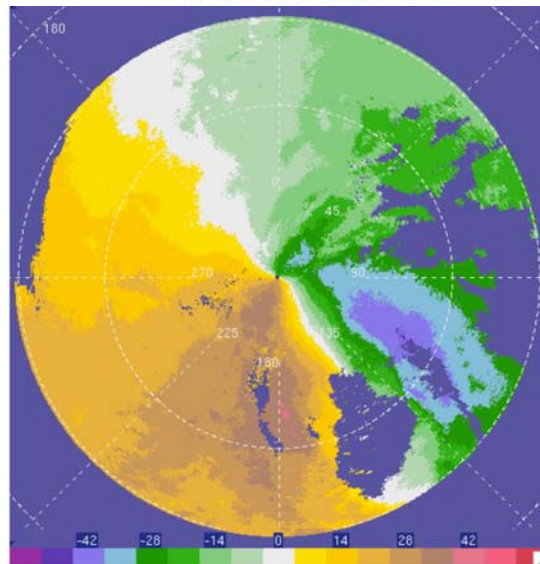
Airborne Vr Super-Observations (SOs): Similar to W88D but more QCs

Airborne
20050920
15:41→16:21

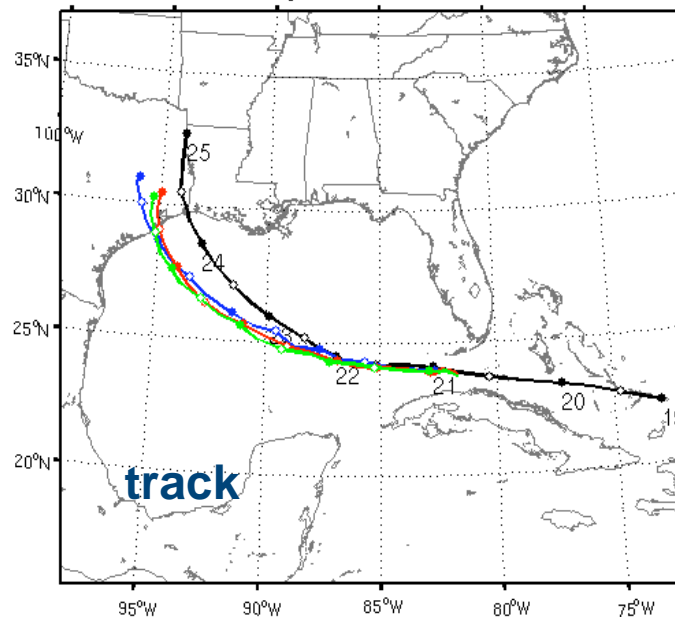
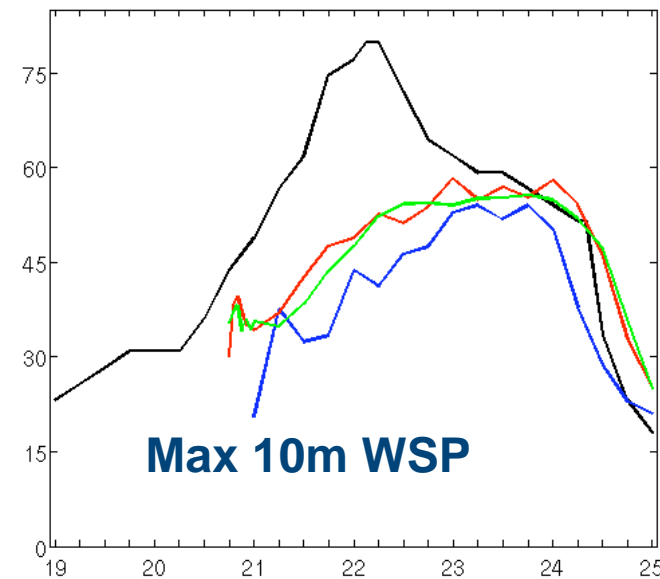
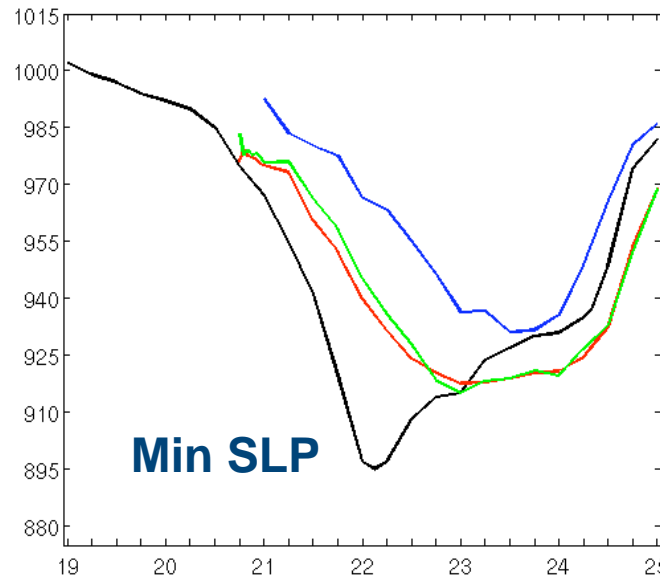


All SOs

KBYX
20050920
15:55:56'
1.50 degree
elevation



Forecasts from EnKF with Airborne vs. NEXRAD



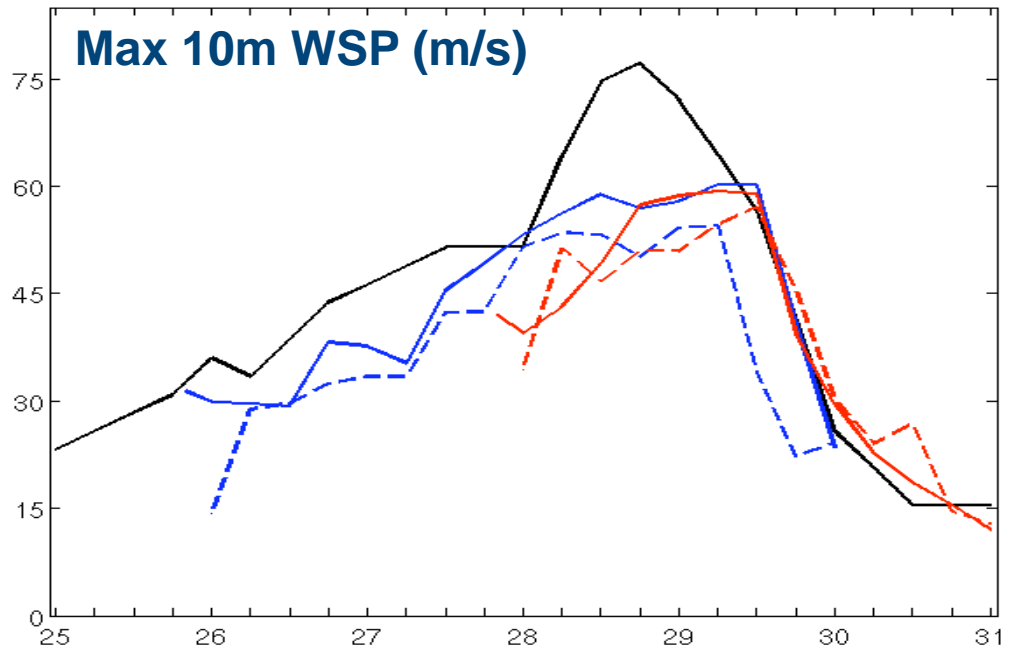
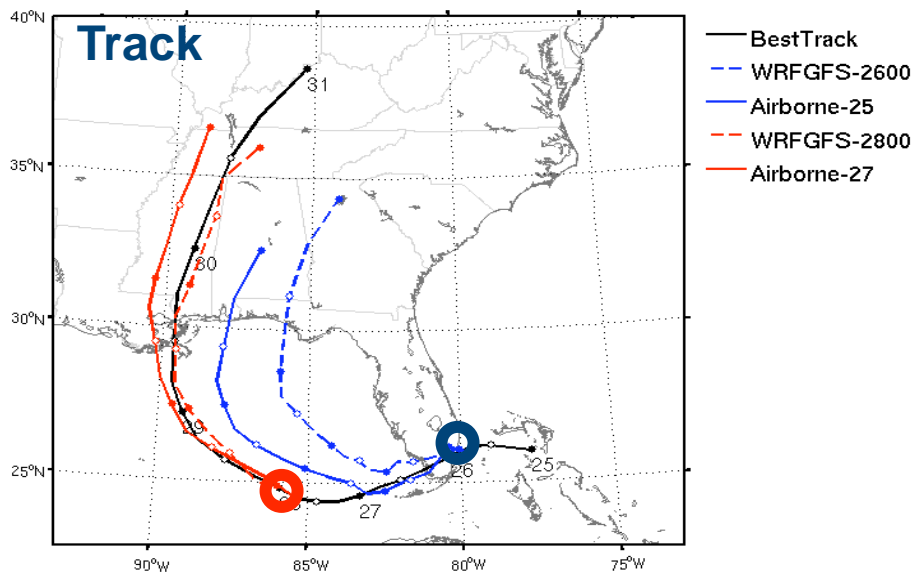
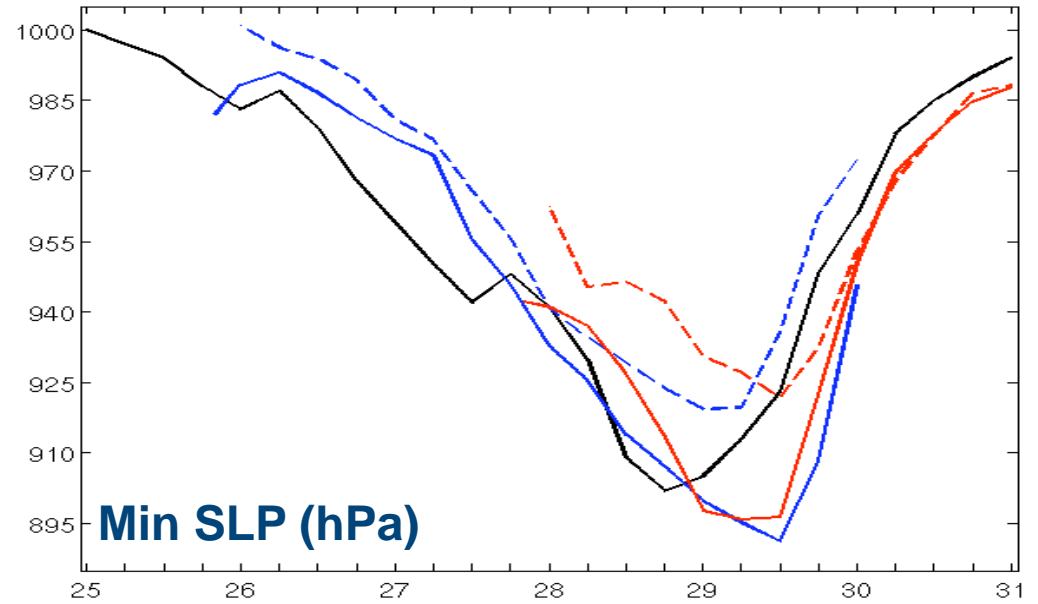
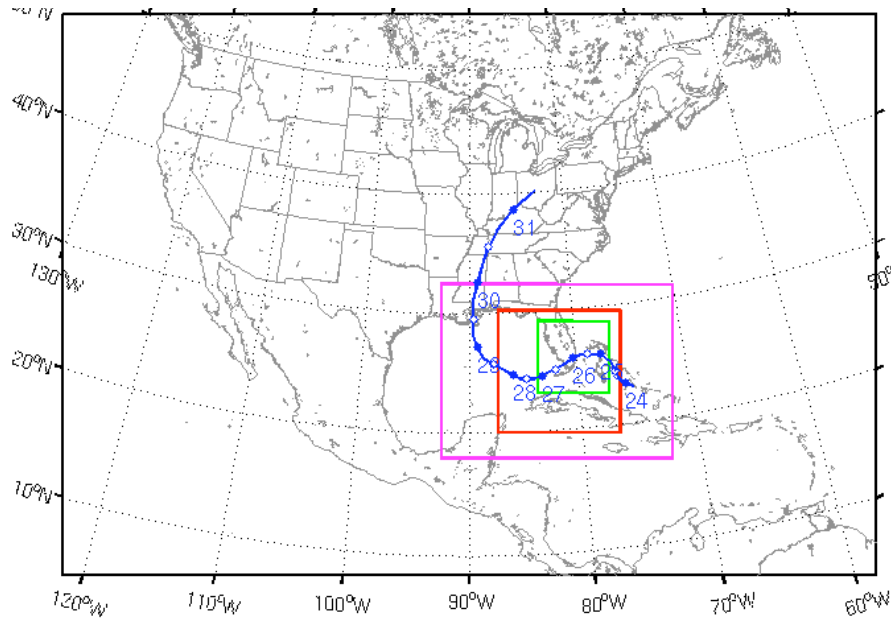
— Best Track
— WRF GFS-2100
— Airborne-20
— KBYX-20

WRF GFS-2100: WRF deterministic forecast took GFS 0000UTC Sep21 analysis as IC and its forecast as BC;

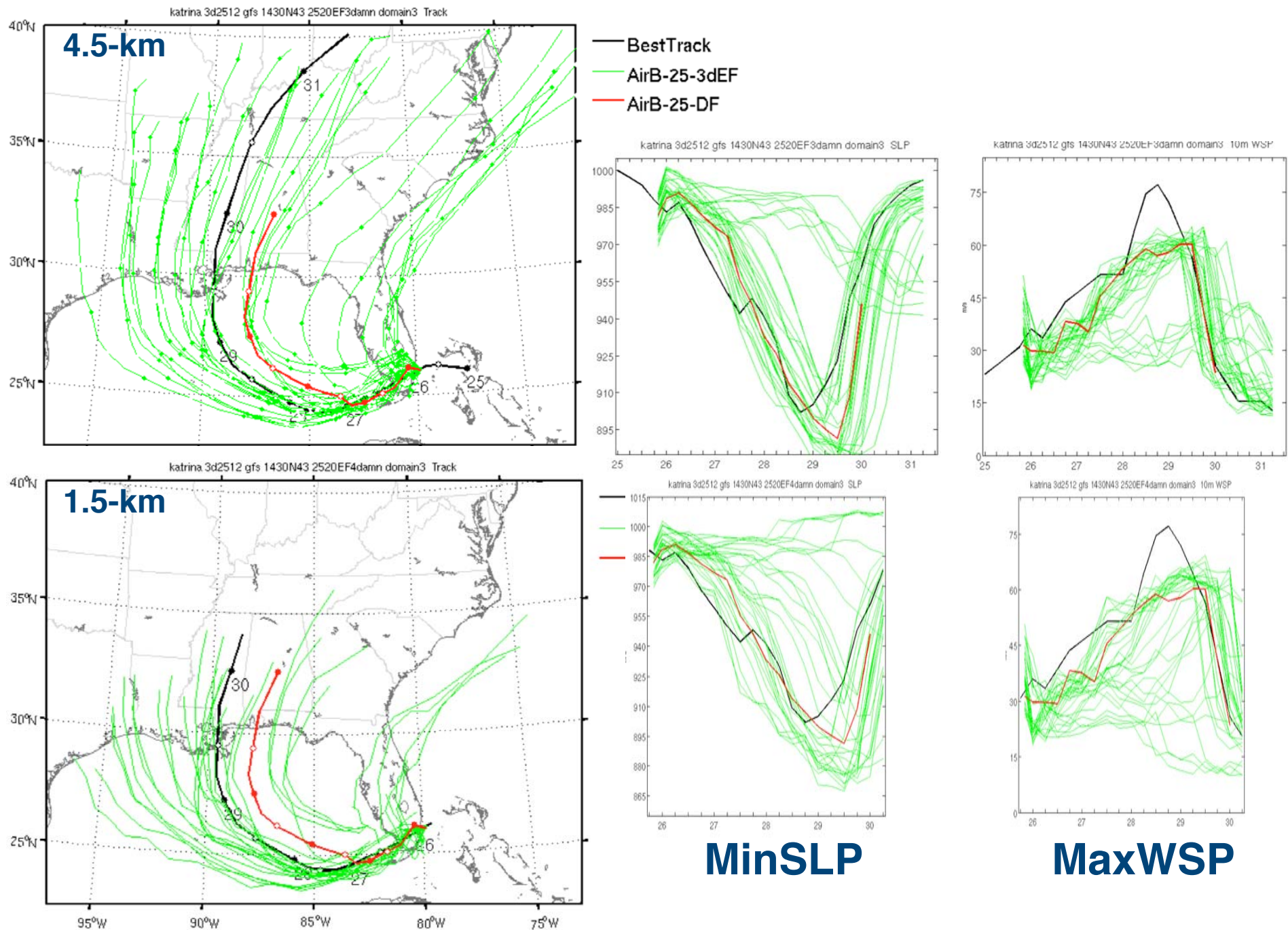
Airborne-20: WRF DF from the EnKF analysis at 1800UTC Sep20 which assimilated N43 Vr at 1600, 1730 and 1800UTC Sep20;

KBYX-20: WRF DF from the EnKF analysis at 1800UTC Sep20 which assimilated KBYX Vr at 1600, 1700 and 1800Z Sep20.

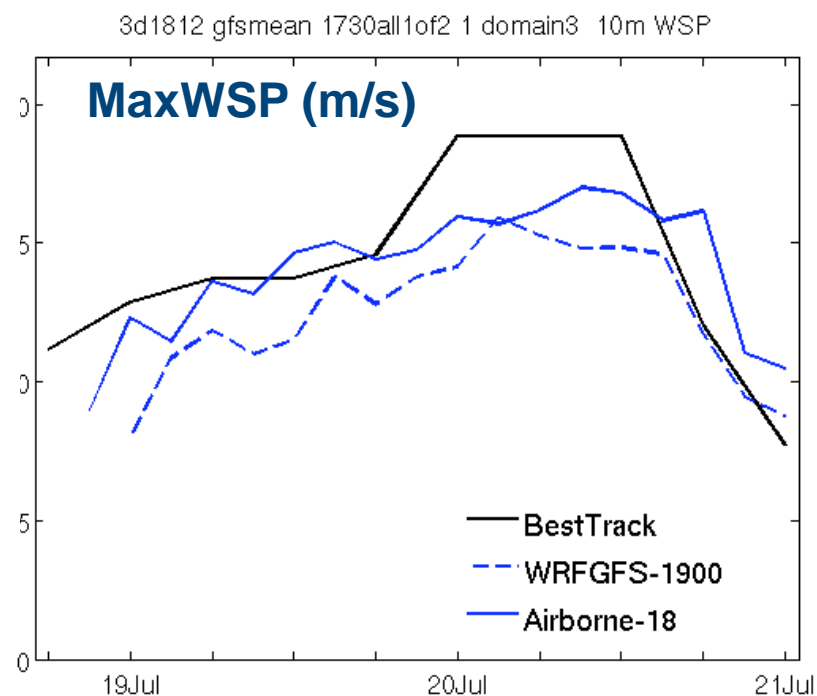
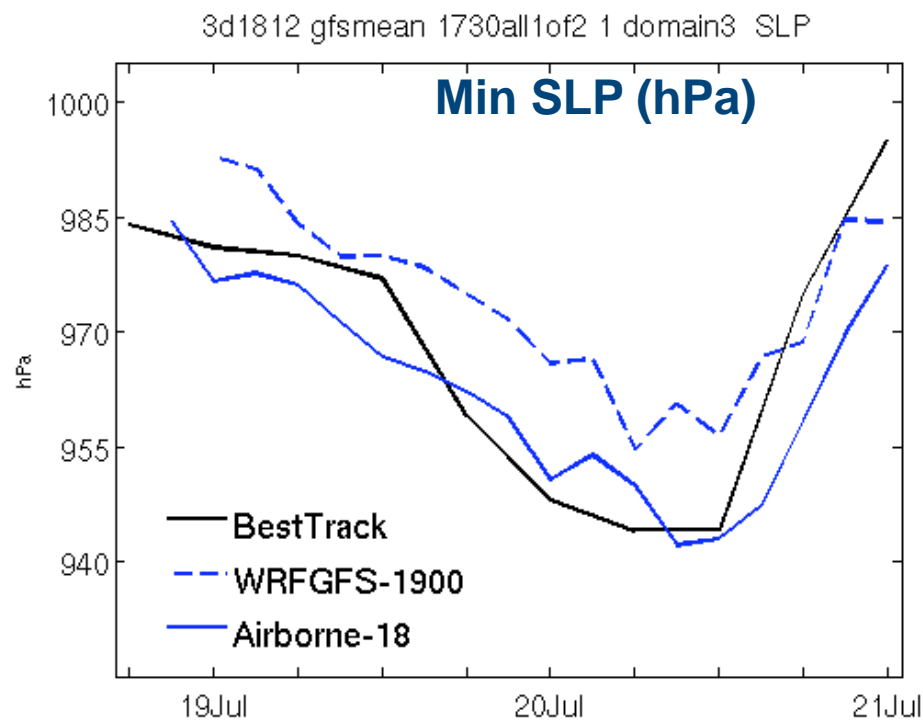
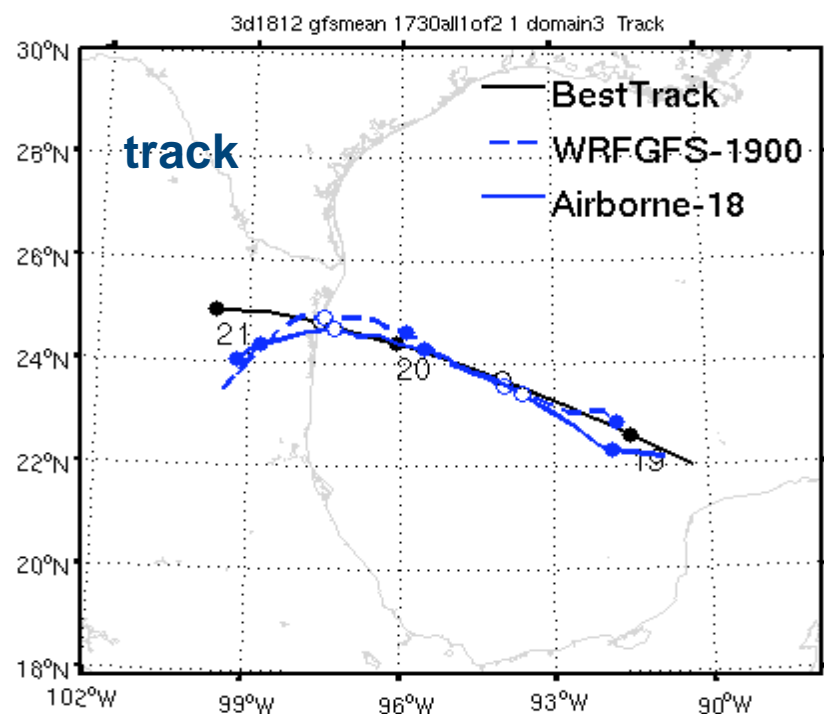
Impacts of Airborne Vr EnKF for Katrina (2005)



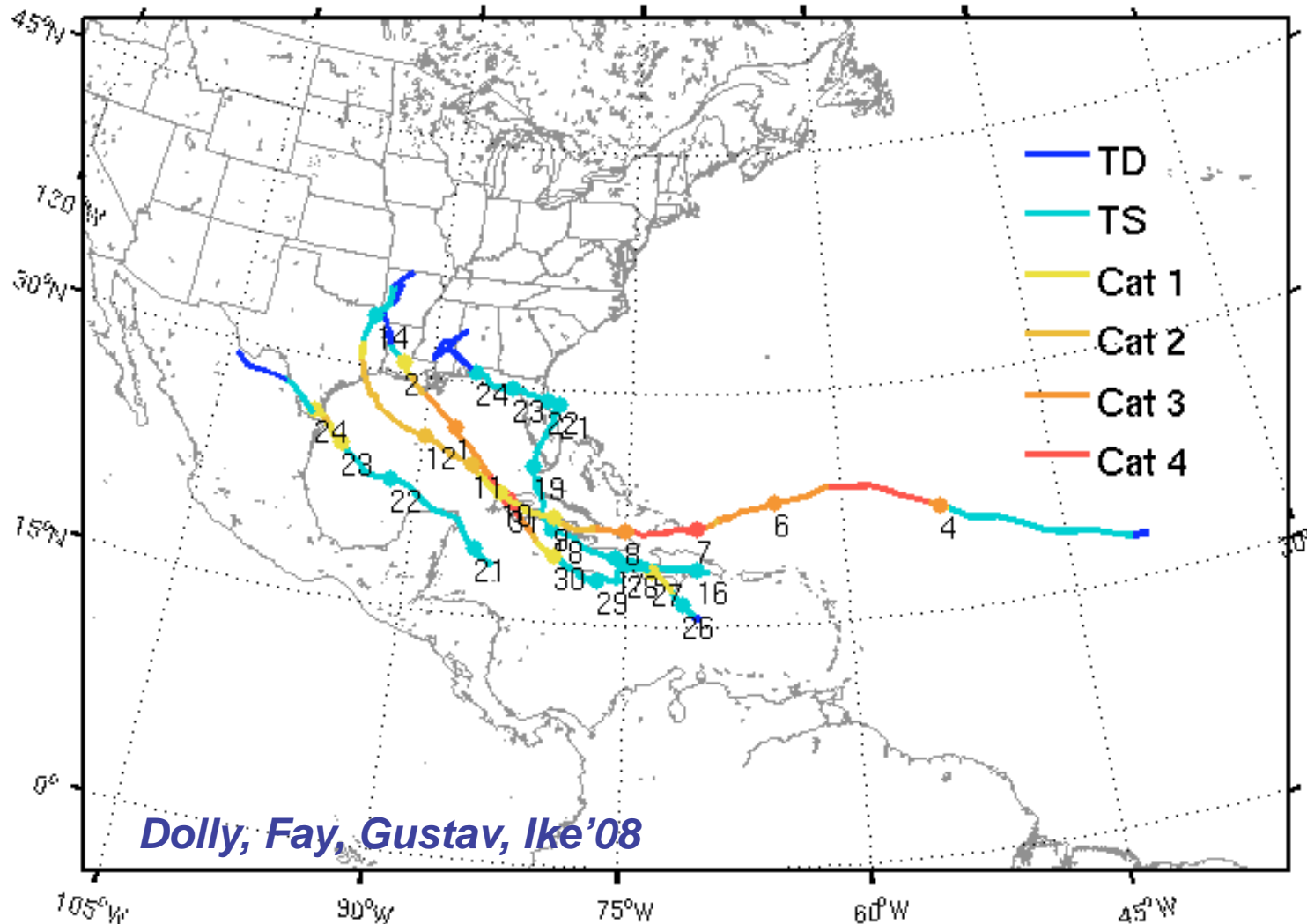
4.5-km (top, 126h) vs. 1.5-km (bottom, 102h) ensemble fcsts



Hurricane Emily (2005): WRF/ARW Forecasts from GFS vs. EnKF



TOWARDS REALTIME ASSIMILATION OF DOPPLER RADAR OBSERVATIONS FOR CLOUD- RESOLVING HURRICANE PREDICTION



Thanks to John Gamache, our Vr superobbing procedure is now implemented on P3 in realtime

NOAA HFIP Use of TACC Computing

GOAL:

1. Make progress on establishing operational value of higher resolution modeling (global and hurricane, including ensembles) to improving forecast performance.
2. Demonstrate potential of on-demand computing to hurricane forecast operations.
3. Inform future R&D needs for HFIP goals and objectives toward the development and implementation of next-generation HFS.
4. Focus research to provide tangible benefit within 3 - 5 years.

System Name: Ranger
Operating System: Linux
Number of Cores: 62,976
Total Memory: 123TB
Peak Performance: 579.4TFlops
Total Disk: 1.73PB (shared)
NOAA Allocation : 30M SUs
(until 1 Jan 2009)
PI for the allocation: Frank Marks



TEXAS ADVANCED COMPUTING CENTER

Powering Discoveries That Change The World



HFIP-TACC On-demand Test

- Diverse NOAA (HRD, ESRL, NCEP/NHC, NCO, EMC) and university (PSU, TAMU, TACC) team established on-demand capability to support operational hurricane forecasting.
- Built upon HFIP high-resolution test plan to use high resolution global (FIM at 15-km) and regional (ARW at 1.5-km using EnKF to assimilate Doppler radar superobs) models to demonstrate on-demand capability.
- NCEP model fields and Doppler radar superobs from NOAA P-3 aircraft flow automatically to TACC, research models run, output products generated for forecasters, and products transferred to NHC via NCO.
- Portions of process tested during Dolly and Fay, with a test of complete system during Gustav and Ike.

Towards Real-time Assimilation of Airborne Radar Observations with EnKF: Same *Experimental Design as Test Cases*

WRF/ARW triply-nested domains for both EnKF analyses and free forecasts:

D1: 121x160x40.5km x 35 levels (similar to GFDL coarse domain)

D2: 121x160x13.5km x 35 levels

D3: 253x253x 4.5km x 35 levels (moving nest in forecast mode)

Time performance of standard real-time WRF/ARW forecast initialized with GFS

Waiting time for GFS completion: 4.5 h

Transfer GFS analysis and forecasts from NCEP to TACC: 0.3 h

Initialization of WRF/ARW with GFS using WPS: 0.4 h

126-h WRF free forecast with 512 processors: 2.7 h

Total time lapse: 7.9 h (**3.4 h after GFS completion**, 1.5 km is 7 h after)

Estimated real-time WRF/ARW forecast initialized assimilating airborne Vr data

EnKF ensemble initialized with most recent available GFS: no waiting time

Quality control and super-observation (SO) of Airborne data per hour: 0.3h

Transfer airborne ~3000 SOs from P3 to TACC: 0.2 h

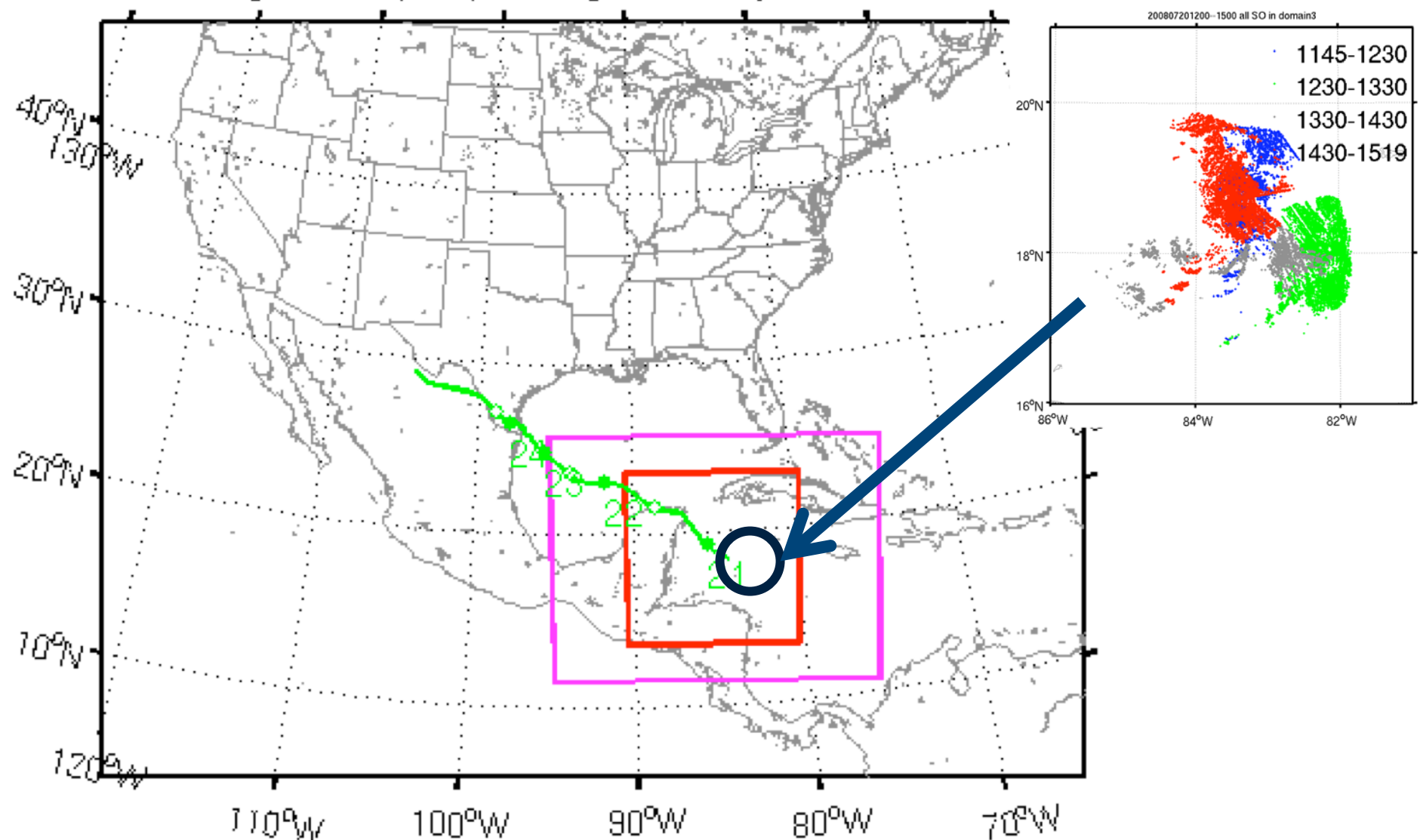
EnKF assimilation of 1-h SOs: 0.5 h

126-h WRF free forecast with 512 processors: 2.7 h

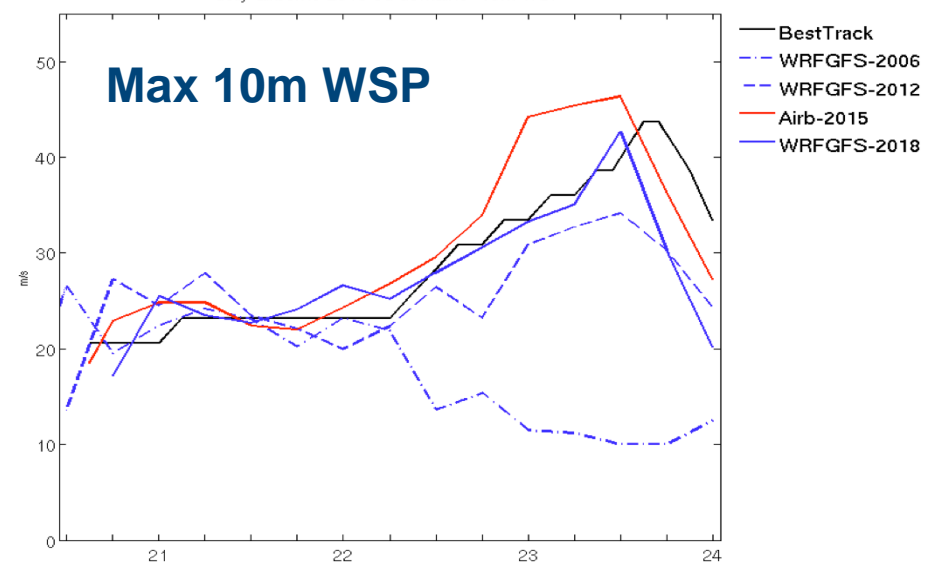
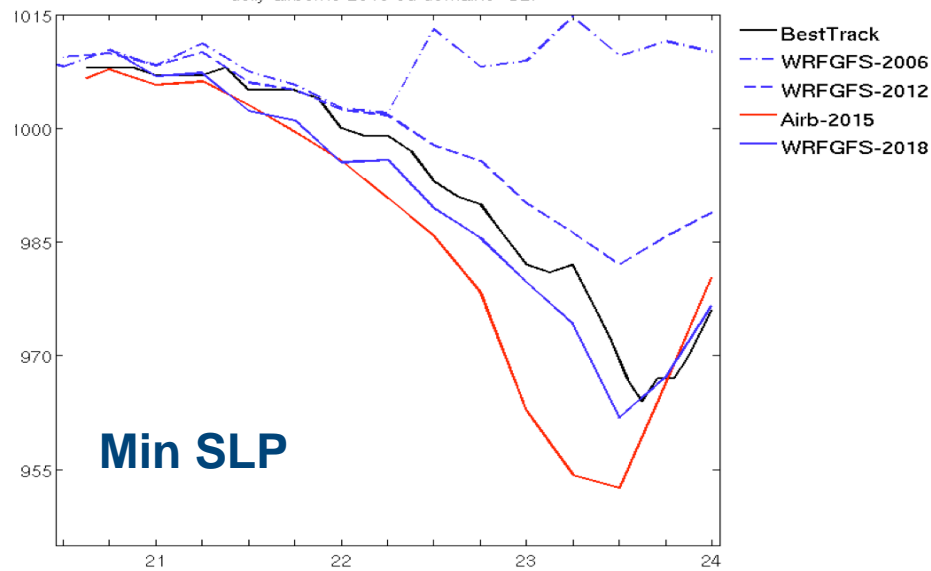
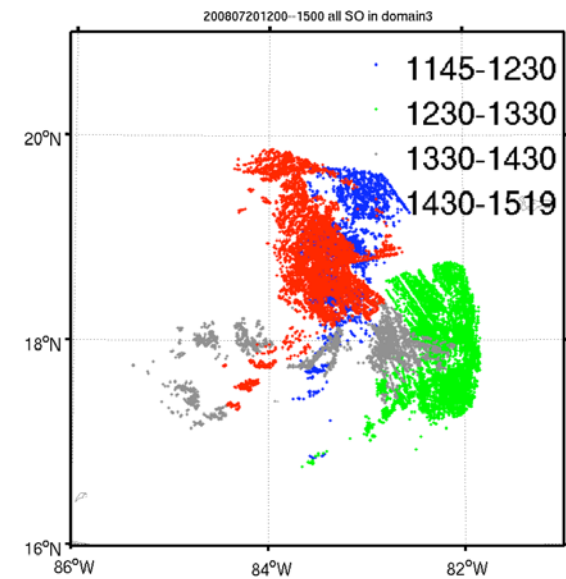
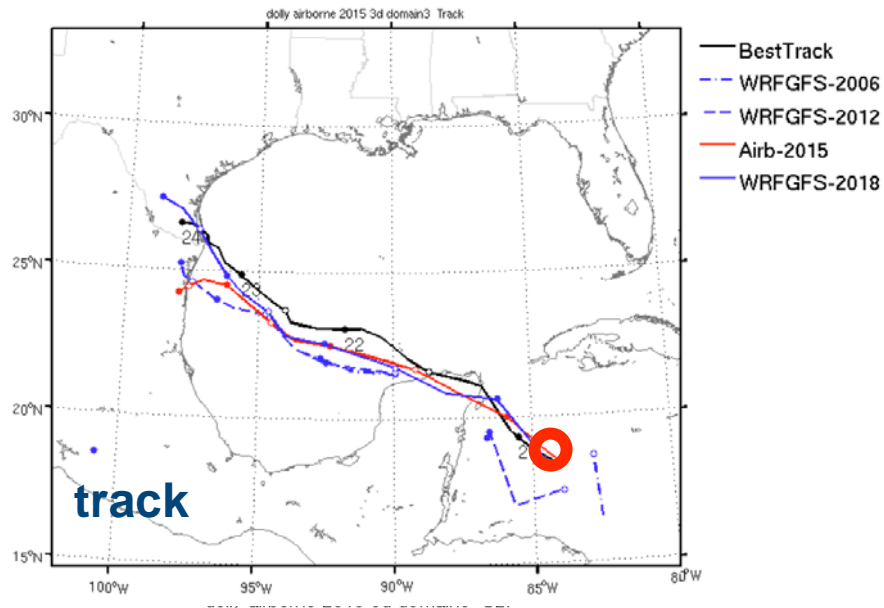
Total time lapse: **3.7 h** (1.5-km is 7 h) **after Doppler observations taken**

Near-realtime Tests of Hurricane Dolly (2008)

SOs Generated shortly after P3 mission

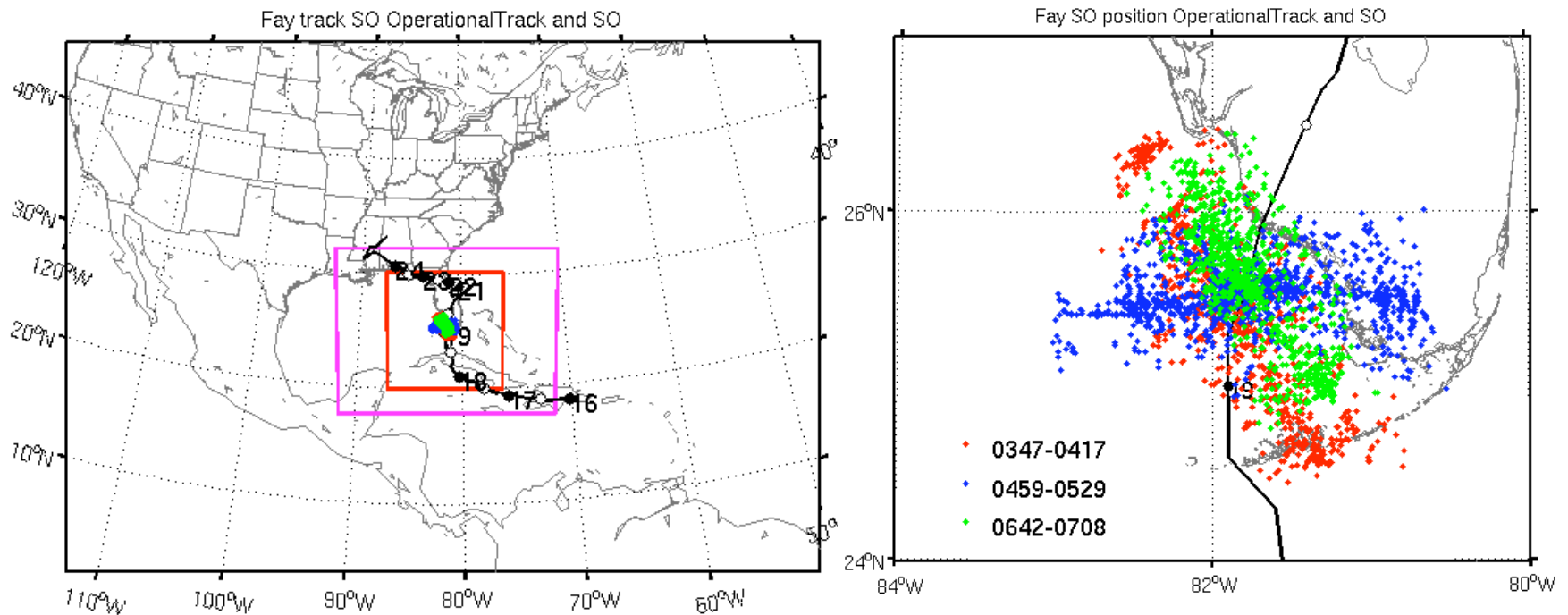


Performance of Airborne Vr Assimilation for Dolly (2008)



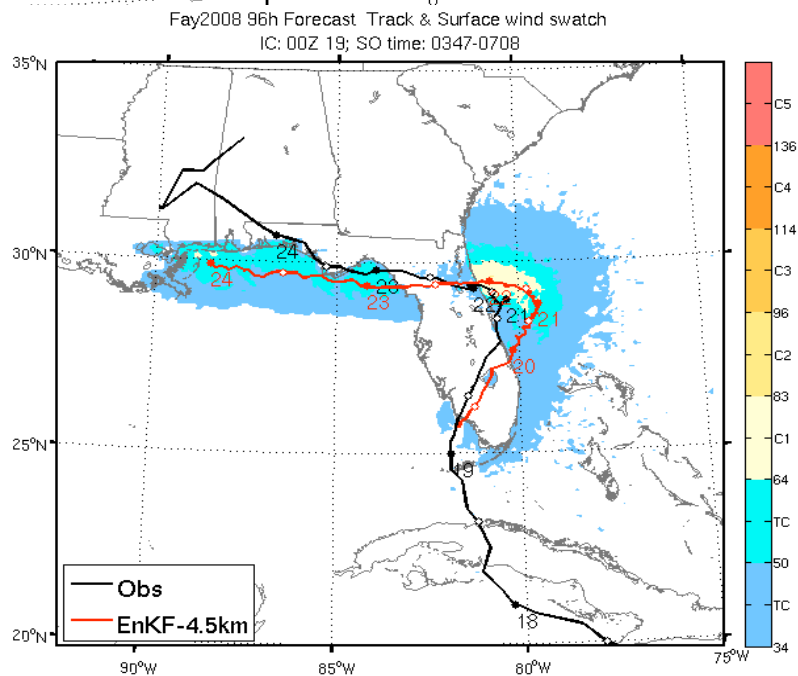
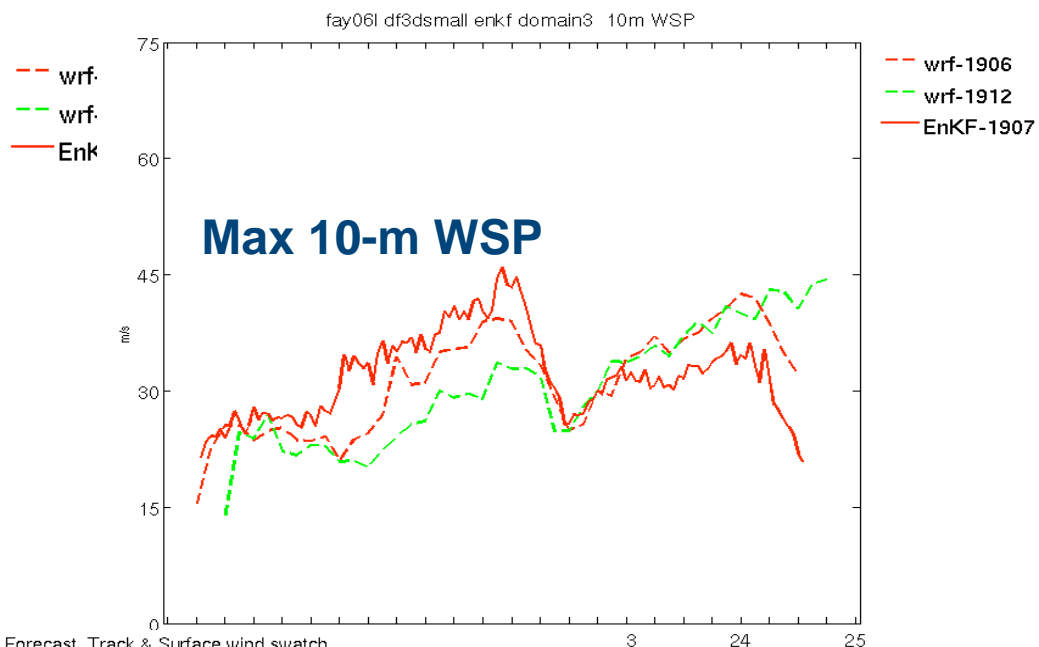
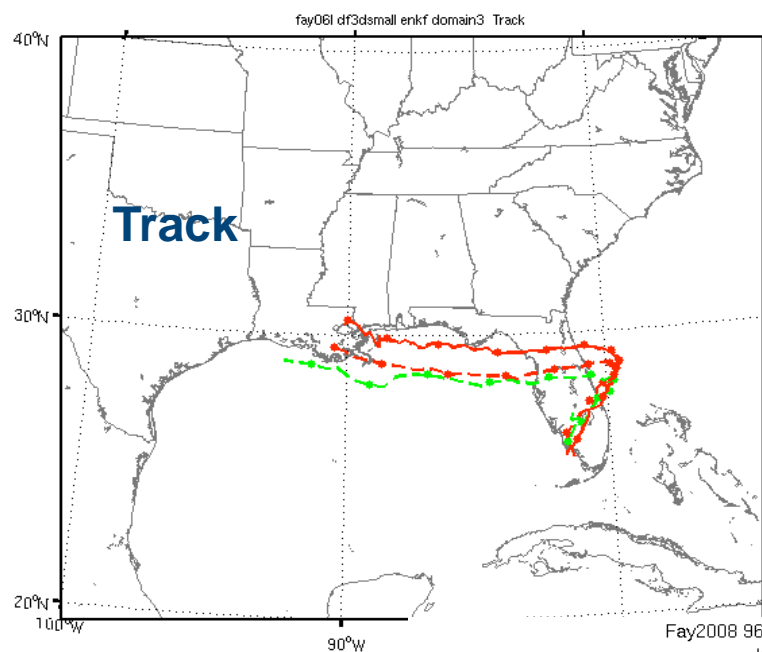
Near-realtime Tests of Hurricane Fay (2008)

SOs Generated during P3 mission and are assimilated a few hours later



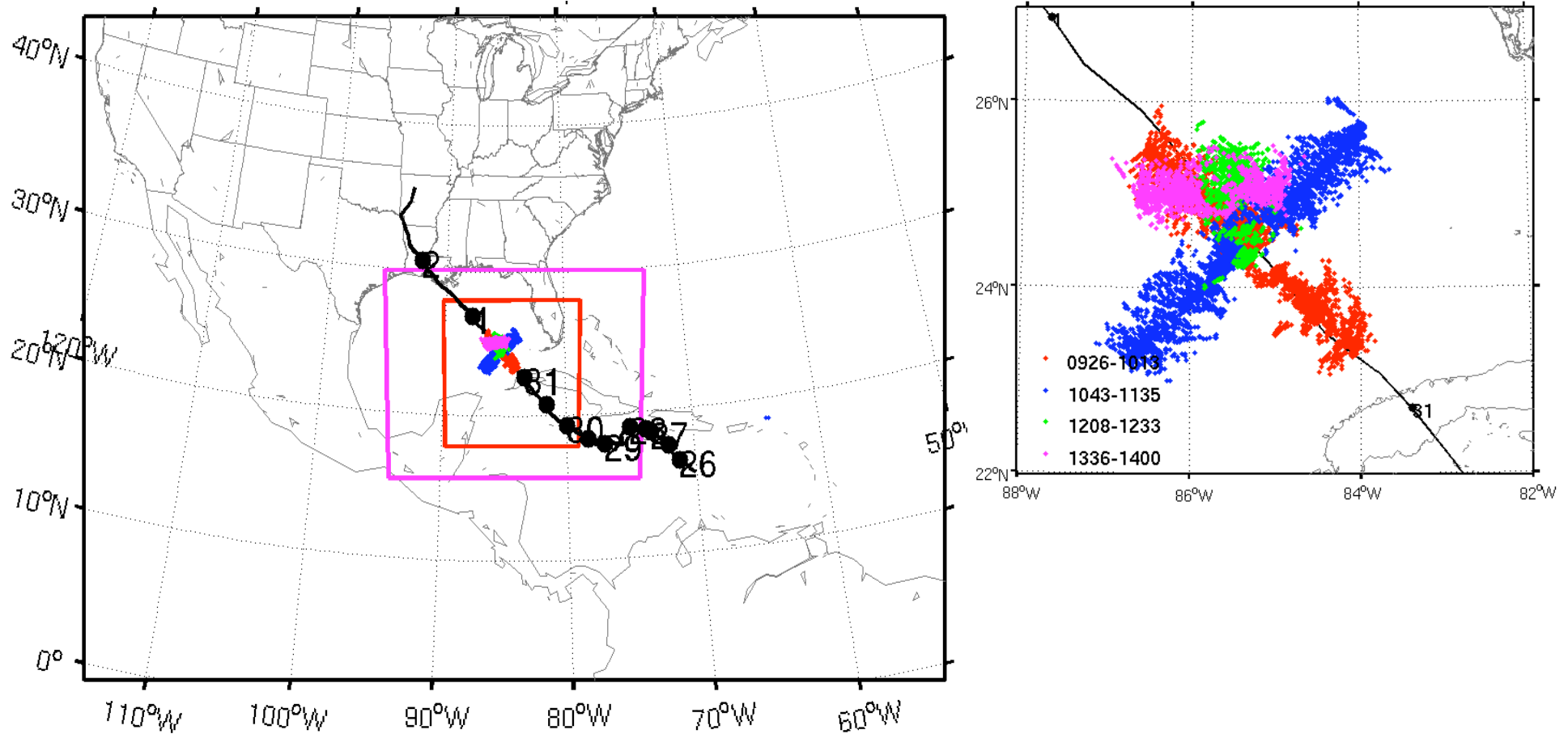
ARW from GFS at 00Z/19; Vr SOs during 3-07Z/19

Impact of Airborne Vr OBS for Fay



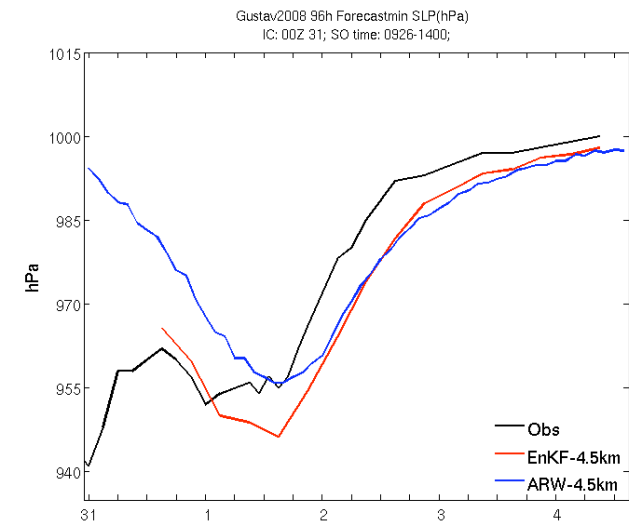
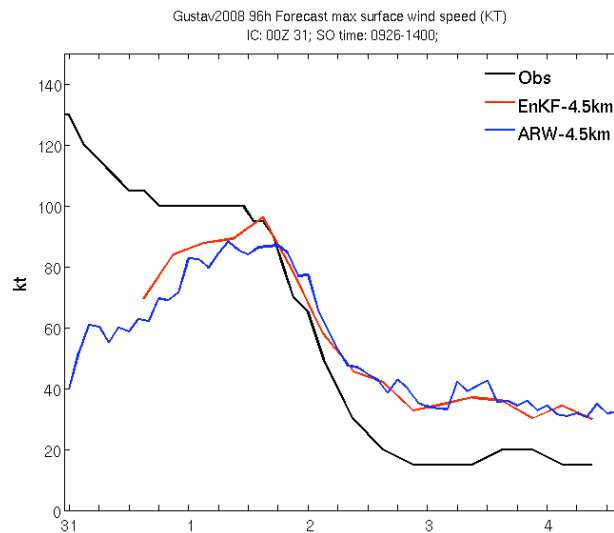
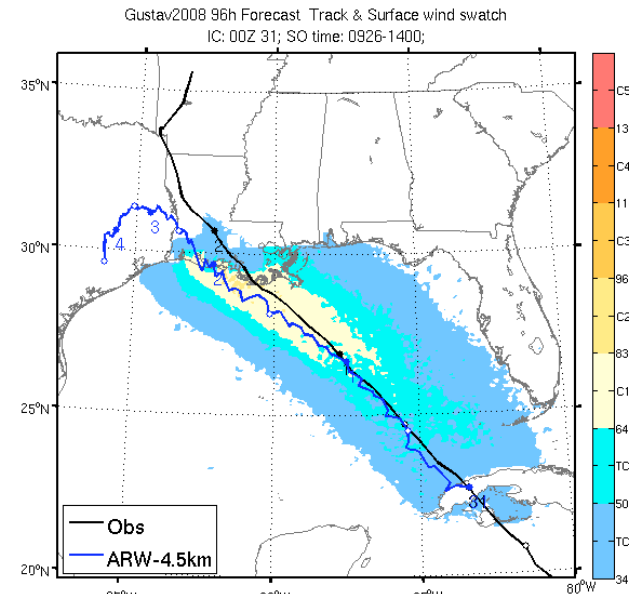
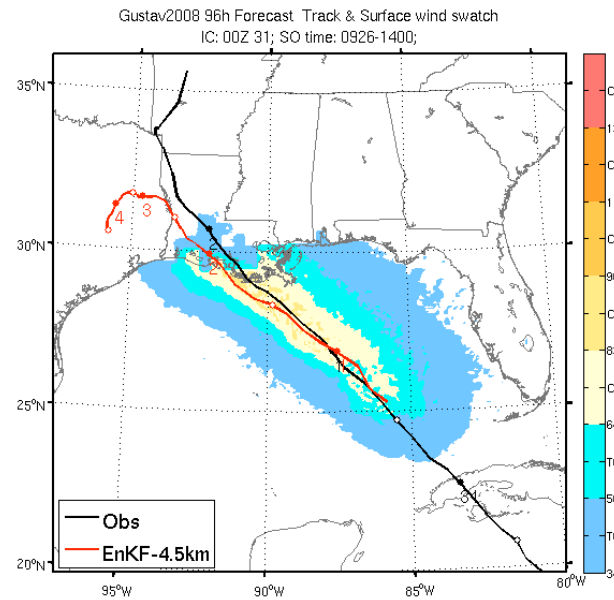
Realtime Tests of Hurricane Gustav (2008)

SOs Generated/assimilated during P3 mission



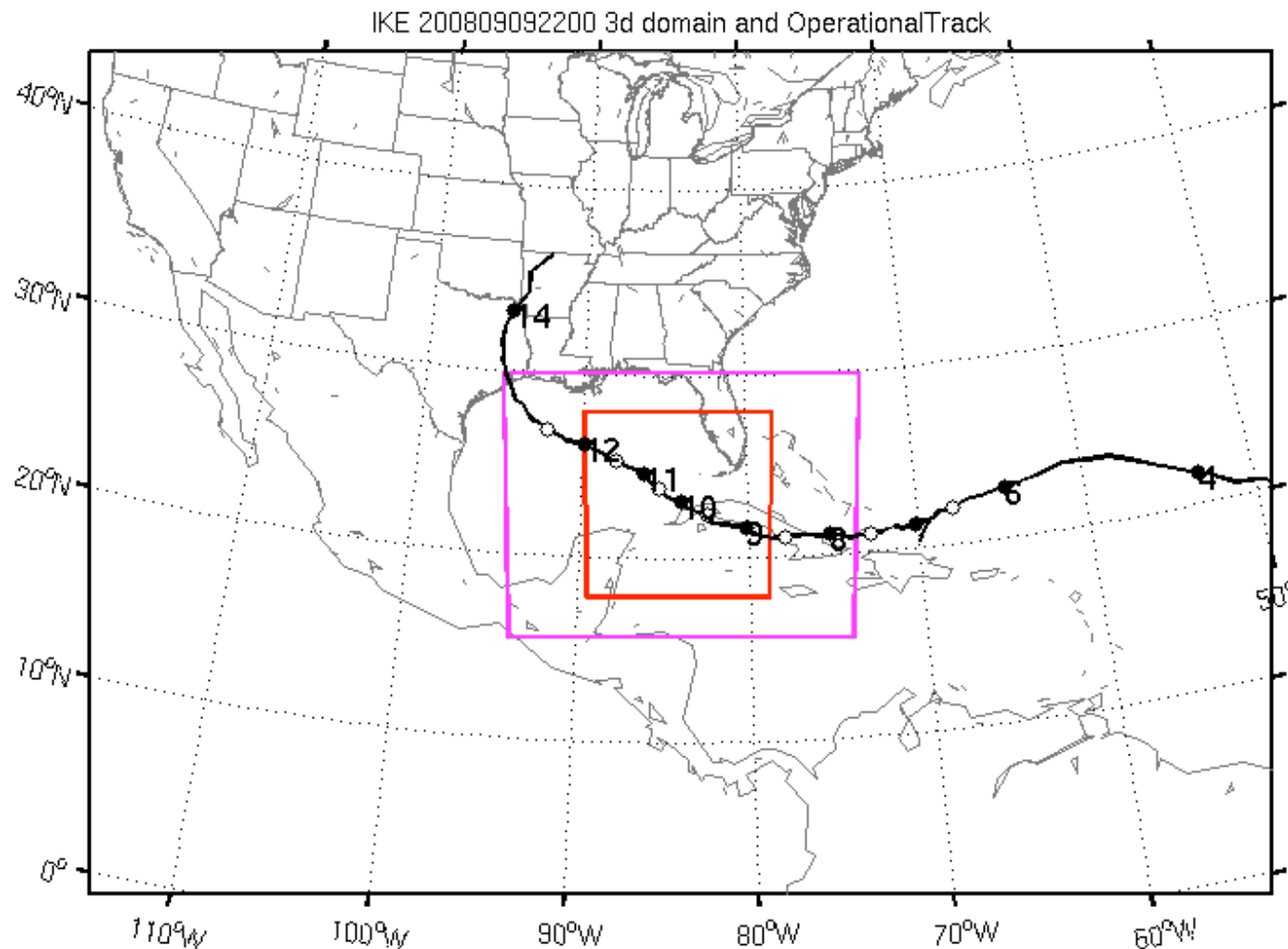
ARW from GFS at 00Z/31; Vr SOs during 9-14Z/31

Impact of Airborne Vr for Gustav



Realtime Tests of Hurricane Ike (2008)

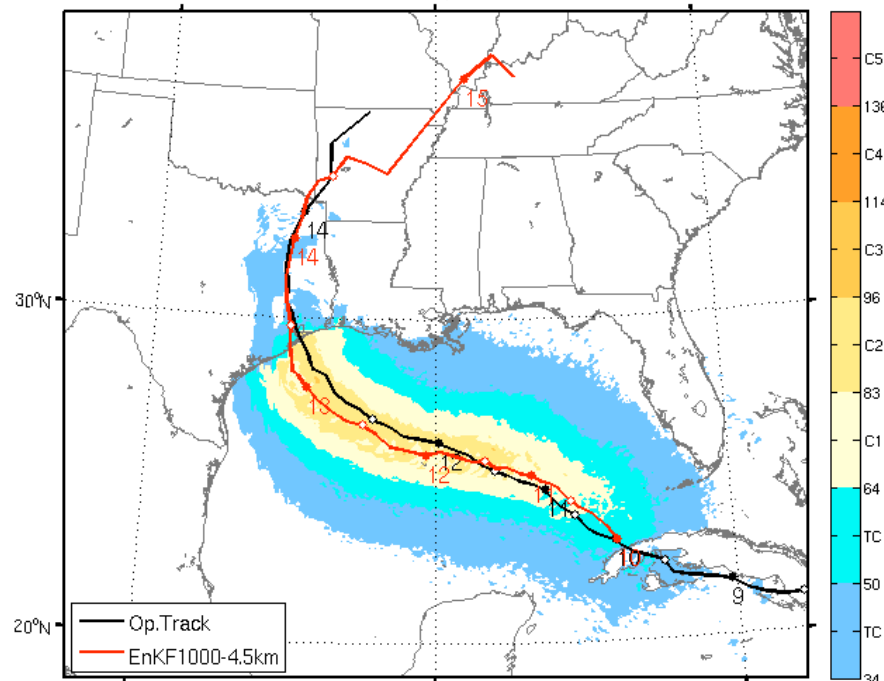
SOs Generated/assimilated during P3 mission



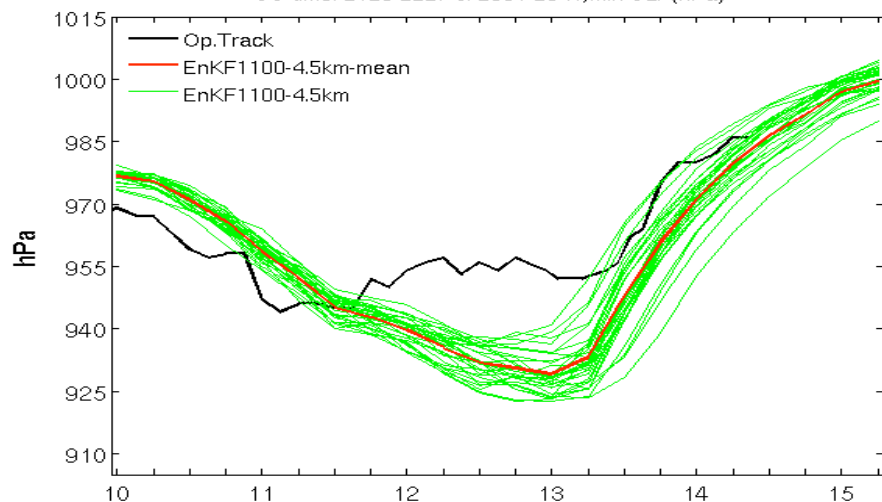
ARW from GFS at 12Z/9; Vr SOs during 21-24Z/09

Realtime ARW Performance with Vr EnKF

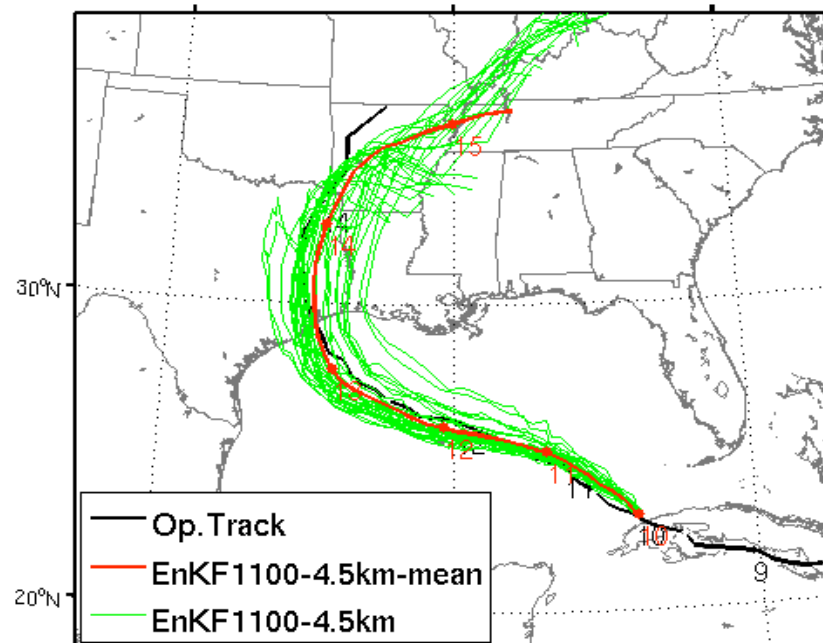
IKE2008 126h Forecast EnKF1000-4.5km
SO time: 2125-2227 & 2302-2341; Track & Surface wind swath



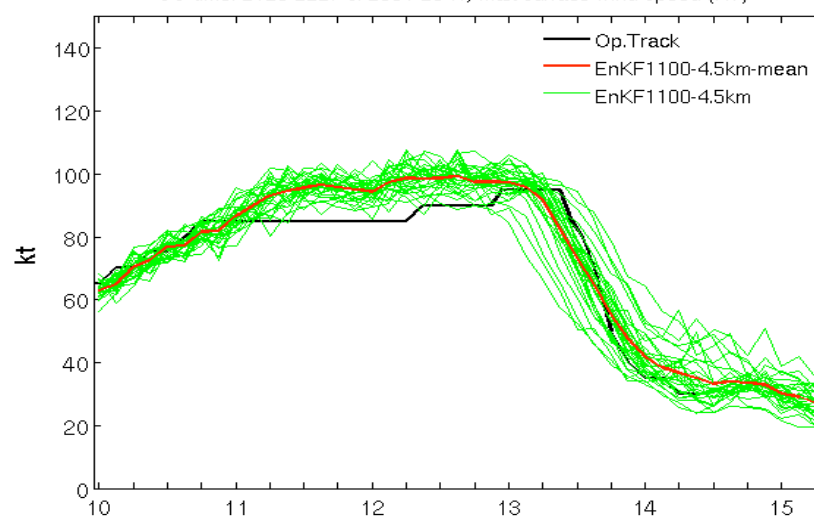
IKE2008 126h 4.5km Ensemble Forecast started at 2008091000
SO time: 2125-2227 & 2301-2341; min SLP(hPa)



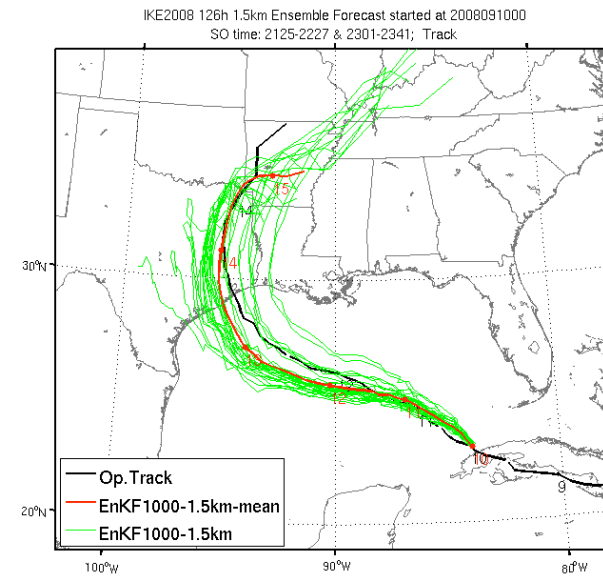
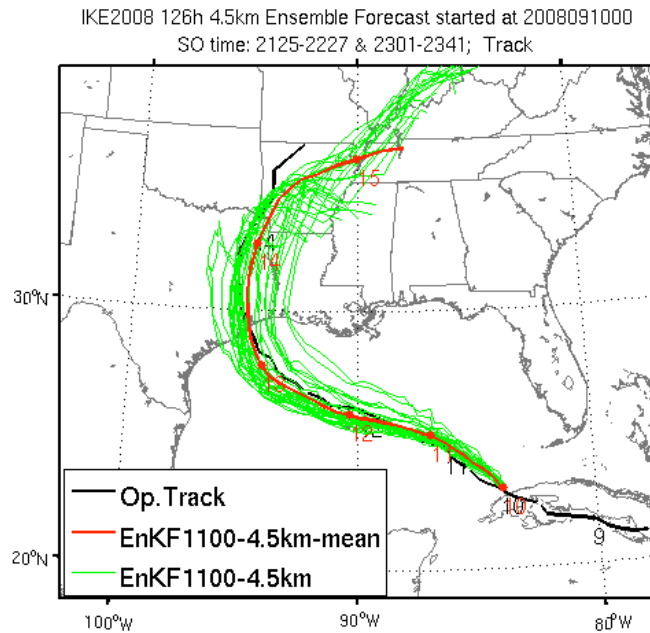
IKE2008 126h 4.5km Ensemble Forecast started at 2008091000
SO time: 2125-2227 & 2301-2341; Track



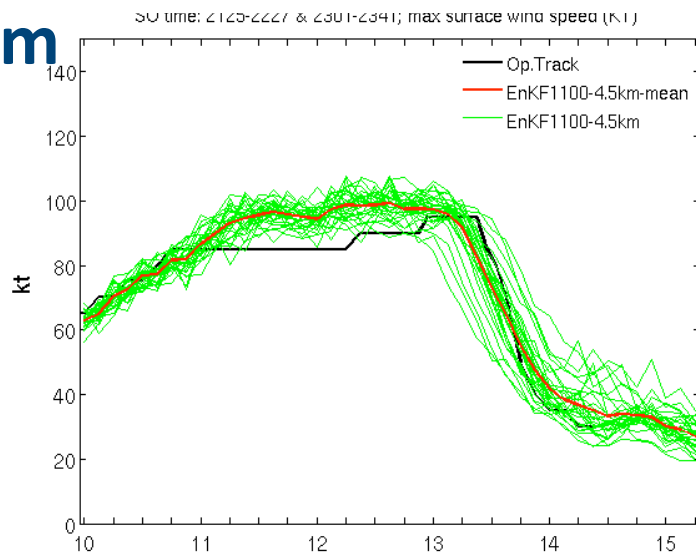
IKE2008 126h 4.5km Ensemble Forecast started at 2008091000
SO time: 2125-2227 & 2301-2341; max surface wind speed (KT)



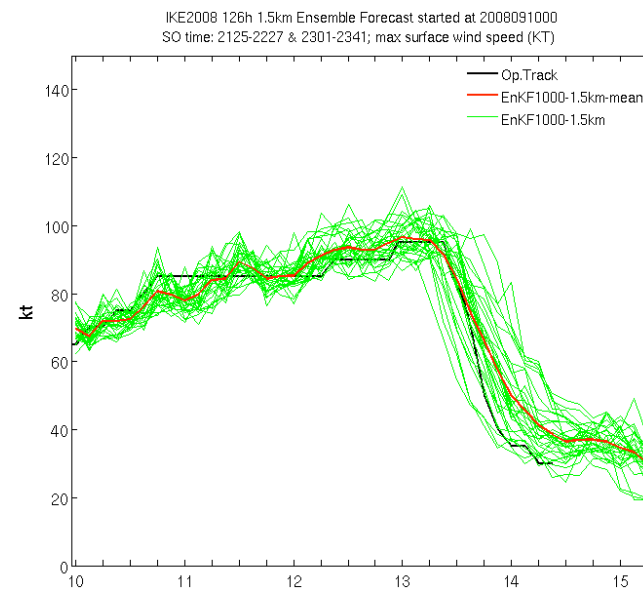
Realtime: Ensemble Sensitivity to Resolution



4.5km



1.5km



Concluding Remarks

- EnKF assimilation with both the ground-based and airborne radar observations into cloud-resolving mesoscale models is promising for initializing hurricanes near observed intensity and for subsequent forecast
- The impacts of airborne Vr are similar to WSR-88D Vr
- EnKF combines data assimilation and ensemble forecast that provides flow-dependent analysis/forecast uncertainty
- Real-time, on-demand, convective-resolving ensemble analysis and forecast experiments on NSF HPC facility assimilating airborne Doppler observations shows great promises for the future of hurricane prediction
- WRF/ARW forecasts are surprisingly similar for the 4.5-km and 1.5-km grid spacings; 4.5-km grid very practical

Experimental Design Using EnKF to Assimilate Airborne Radar Observations: *Towards Potential Real-time Applications*

